www.nodia.co.in www. www.nodia.co.in www. www.nodia.co.in www.			
MEE Control of the second seco	A contraction www.nodia.co.in	co.in co.in co.in co.in co.in co.in co.in co.in co.in co.in co.in	
MCQ 1.1 GATE ME 2008 ONE MARK	In the Taylor series expansion of $e^x$ about $x = 2$ , the coefficient of $(x-2)^4$ is (A) 1/4 ! (B) $2^4/4!$ (C) $e^2/4!$ (D) $e^4/4!$		
SOL 1.1	Option (C) is correct. Taylor's series expansion of $f(x)$ is given by, $f(x) = f(a) + \frac{(x-a)}{\underline{1}}f'(a) + \frac{(x-a)^2}{\underline{2}}f''(a) + \frac{(x-a)^3}{\underline{3}}f'''(a) + \dots$ Then from this expansion the coefficient of $(x-a)^4$ is $\frac{f'''(a)}{\underline{4}}$ Given a = 2 & $f(x) = e^x$ $f'(x) = e^x$ $f''(x) = e^x$ $f'''(x) = e^x$ $f'''(x) = e^x$ $f'''(x) = e^x$ $f'''(x) = e^x$ Hence, for $a = 2$ the coefficient of $(x-a)^4$ is $\frac{e^2}{2}$		
MCQ 1.2 GATE ME 2008 ONE MARK	Given that $\ddot{x} + 3x = 0$ , and $x(0) = 1$ , $\dot{x}(0) = 0$ , what is $x(1)$ ? (A) $-0.99$ (B) $-0.16$ (C) $0.16$ (D) $0.99$		
SOL 1.2	Option (D) is correct. Given : $\ddot{x} + 3x = 0 \& x(0) = 1$ $(D^2 + 3) x = 0$ The auxiliary Equation is written as $m^2 + 3 = 0$ $m = \pm \sqrt{3} i = 0 \pm \sqrt{3} i$ Here the roots are imaginary $m_1 = 0 \& m_2 = \sqrt{3}$	$\frac{d}{dt}$	

Brought to you by: Nodia and Company PUBLISHING FOR GATE

Visit us at: www.nodia.co.in

Page 2

& Solution is given by  

$$x = e^{n/4} (A \cos m_2 t + B \sin m_2 t)$$

$$x = e^0 [A \cos \sqrt{3} t + B \sin \sqrt{3} t]$$

$$= [A \cos \sqrt{3} t + B \sin \sqrt{3} t]$$
...(i)  
Given :  $x(0) = 1$  at  $t = 0, x = 1$   
Substitute in equation (i),  
 $1 = [A \cos \sqrt{3} (0) + B \sin \sqrt{3} (0)] = A + 0$   
 $A = 1$   
Differentiate equation (i) w.r.t. t,  
 $\dot{x} = \sqrt{3} [-A \sin \sqrt{3} t + B \cos \sqrt{3} t]$ 
...(ii)  
Given  $\dot{x}(0) = 0$  at  $t = 0, \dot{x} = 0$   
Substitute in equation (ii), we get  
 $0 = \sqrt{3} [-A \sin 0 + B \cos 0]$   
 $B = 0$   
Put  $A \& B$  in equation (i)  
 $x = \cos \sqrt{3} t = 0.399$   
MCQ 1.3  
The value of  $\lim_{x \to 8} \frac{d^{2/3} - 2}{x + 8}$   
 $(A) \frac{1}{16}$   
(C)  $\frac{1}{8}$   
Sol 1.3 Option (B) is correct.  
Let  $f(x) = \lim_{x \to 3} \frac{d^{2/3} - 2}{(x - 8)}$   
(D)  $\frac{1}{4}$   
Sol 4.4 A coin is tossed 4 times. What is the probability of getting heads exactly 3 times ?  
GATE MERSE  
(A)  $\frac{1}{4}$   
(B)  $\frac{3}{8}$   
(C)  $\frac{1}{2}$   
(D)  $\frac{1}{4}$   
Sol 1.4 Option (A) is correct.  
In a coin probability of getting Head  
 $p = \frac{1}{2} = \frac{N_0, of Possible cases}{N_0, of Total cases}$ 

Brought to you by: Nodia and Company PUBLISHING FOR GATE

Visit us at: www.nodia.co.in

Probability of getting tail

 $q = 1 - \frac{1}{2} = \frac{1}{2}$ 

So the probability of getting Heads exactly three times, when coin is tossed 4 times is

$$P = {}^{4}C_{3}(p)^{3}(q)^{1}$$
  
=  ${}^{4}C_{3}\left(\frac{1}{2}\right)^{3}\left(\frac{1}{2}\right)^{1} = 4 \times \frac{1}{8} \times \frac{1}{2} = \frac{1}{4}$ 

**MCQ 1.5** GATE ME 2008 ONE MARK

The matrix  $\begin{vmatrix} 3 & 0 & 6 \\ 1 & 1 & p \end{vmatrix}$  has one eigen value equal to 3. The sum of the other two eigen value is (B) p - 1(D) p - 3

0 6

Option (C) is correct. **SOL 1.5** 

(C) p-2

(A) p

Let.

1 pLet the eigen values of this matrix are  $\lambda_1, \lambda_2 \& \lambda_3$ Here one values is given so let  $\lambda_1 = 3$ We know that

Sum of eigen values of matrix = Sum of the diagonal element of matrix A  $\lambda_1 + \lambda_2 + \lambda_3 = 1 + 0 + p$ 

$$\lambda_2 + \lambda_3 = 1 + p - \lambda_1 = 1 + p - 3$$
$$= p - 2$$

The divergence of the vector field  $(x - y)\mathbf{i} + (y - x)\mathbf{j} + (x + y + z)\mathbf{k}$  is **MCQ 1.6** GATE ME 2008 (A) 0(B) 1 ONE MARK (D) 3 (C) 2

**SOL 1.6** Option (D) is correct. We know that the divergence is defined as  $\nabla \cdot V$ 

Now that the divergence is defined as 
$$\mathbf{v} \cdot \mathbf{v}$$
  
 $\mathbf{V} = (x - y)\mathbf{i} + (y - x)\mathbf{j} + (x + y + z)\mathbf{k}$ 

And

So,

Let

$$\nabla = \left(\frac{\partial}{\partial x}\mathbf{i} + \frac{\partial}{\partial y}\mathbf{j} + \frac{\partial}{\partial z}\mathbf{k}\right)$$
$$\nabla \cdot \mathbf{V} = \left(\frac{\partial}{\partial x}\mathbf{i} + \frac{\partial}{\partial y}\mathbf{j} + \frac{\partial}{\partial z}\mathbf{k}\right) \cdot \left[(x - y)\mathbf{i} + (y - x)\mathbf{j} + (x + y + z)\mathbf{k}\right]$$
$$= \frac{\partial}{\partial x}(x - y) + \frac{\partial}{\partial y}(y - x) + \frac{\partial}{\partial z}(x + y + z)$$
$$= 1 + 1 + 1 = 3$$

GATE ME 2008 ONE MARK

The transverse shear stress acting in a beam of rectangular cross-section, subjected



- (A) variable with maximum at the bottom of the beam
- (B) variable with maximum at the top of the beam
- (C) uniform
- (D) variable with maximum on the neutral axis

**SOL 1.7** Option (D) is correct.



For a rectangle cross-section:  $\tau_v = \frac{FA\,\overline{Y}}{Ib} = \frac{6F}{bd^3} \left(\frac{d^2}{4} - y^2\right)$ 

F = Transverse shear load

 $\tau_{mean} = \frac{F}{hd}$ 

Maximum values of 
$$\tau_v$$
 occurs at the neutral axis where,  $y = 0$   
Maximum  $\tau_v = \frac{6F}{bd^3} \times \frac{d^2}{4} = \frac{3F}{2bd}$ 
$$= \frac{3}{2}\tau_{\text{mean}}$$

So, transverse shear stress is variable with maximum on the neutral axis.

**MCQ 1.8** A rod of length L and diameter D is subjected to a tensile load P. Which of the following is sufficient to calculate the resulting change in diameter ? (A) Young's modulus

- (A) Young's modulus
- (B) Shear modulus
- (C) Poisson's ratio
- (D) Both Young's modulus and shear modulus

### **SOL 1.8** Option (D) is correct.



Brought to you by: <u>Nodia and Company</u> PUBLISHING FOR GATE **ME GATE-08** 

From the application of load P, the length of the rod increases by an amount of  $\Delta L$ 

$$\Delta L = \frac{PL}{AE} = \frac{PL}{\frac{\pi}{4}D^2E} = \frac{4PL}{\pi D^2E}$$

And increase in length due to applied load P in axial or longitudinal direction, the shear modulus is comes in action.

$$G = \frac{\text{Shearing stress}}{\text{Shearing strain}} = \frac{\tau_s}{\Delta L/L} = \frac{\tau_s L}{\Delta L}$$

So, for calculating the resulting change in diameter both young's modulus & shear modulus are used.



$$=\frac{\pi/4}{1}=\frac{\pi}{4}$$
 sec



So, increase in length of the rod during this time will be

 $\Delta L(t) = L(t) \times t = \frac{\pi}{4} \times 1 = \frac{\pi}{4} \text{ meter}$ Rod turn  $\frac{\pi}{4}$  radian. So, increased length after  $\frac{\pi}{4}$  sec, (New length)

$$=\left(1+\frac{\pi}{4}\right)=1.785 \text{ m}$$

Now, tangential velocity will be  $R_{t} = R.\omega = 1.785 \text{ m/sec}$   $\omega = \dot{\theta}(t)$ Radial velocity will be  $V_{r} = \dot{L}(t) = 1 \text{ m/sec}$ Therefore, the resultant velocity will be  $V_{R} = \sqrt{V_{t}^{2} + V_{r}^{2}} = \sqrt{(1.785)^{2} + (1)^{2}} = 2.04 \approx 2 \text{ m/sec}$ 



A cantilever type gate hinged at Q is shown in the figure. P and R are the centers of gravity of the cantilever part and the counterweight respectively. The mass of the cantilever part is 75 kg. The mass of the counter weight, for static balance, is





Page 7

First of all we have to make the FBD of the given system.



Let mass of the counter weight = m.

Here point Q is the point of contraflexure or point of inflection or a virtual hinge. So,  $M_Q = 0$  $m \times 0.5 = 75 \times 2 \Rightarrow m = 300 \text{ kg}$ 

MCQ 1.11 A planar mechanism has 8 links and 10 rotary joints. The number of degrees of freedom of the mechanism, using Gruebler's criterion, is

**SOL 1.11** Option (B) is correct.

From Gruebler's criterion, the equation for degree of freedom is given by,

$$n = 3(l-1) - 2j - h$$
 ...(i)

Given 
$$l = 8$$
 and  $j = 10, h = 0$   
 $n = 3(8-1) - 2 \times 10 = 1$  from equation(i)

MCQ 1.12An axial residual compressive stress due to a manufacturing process is present on<br/>the outer surface of a rotating shaft subjected to bending. Under a given bending<br/>load, the fatigue life of the shaft in the presence of the residual compressive stress is

- (A) decreased
- (B) increased or decreased, depending on the external bending load
- (C) neither decreased nor increased
- (D) increased

**SOL 1.12** Option (D) is correct.



The figure shown the Gerber's parabola. It is the characteristic curve of the fatigue

Page 8		ME GATE-08		www.gatehelp.com
	life of the shaft in The fatigue life of compressive mean	n the presence of the residu of the material is effective n stress, whether applied o	al compressive stress. ely increased by the i r residual.	ntroduction of a
MCQ 1.13 GATE ME 2008 ONE MARK	2 moles of oxygen chamber, so that same as those of t constant is given is given by $(A) - R \ln 2$ $(C) R \ln 2$	are mixed adiabatically we the final total pressure and the individual constituents as $R$ . The change in entro (B) (D)	ith another 2 moles of and temperature of the at their initial states. Topy due to mixing, per $0 = 0$ R ln 4	oxygen in mixing mixture become The universal gas mole of oxygen,
SOL 1.13	Option (B) is correct. Given : $T_1 = T_2$ , $p_1 = p_2$ Universal Gas constant = $R$ Here given oxygen are mixed adiabatically So, $dQ = 0$ We know, $ds = \frac{dQ}{dR} = \frac{0}{R} = 0$			
MCQ 1.14 GATE ME 2008 ONE MARK	For flow of fluid of Specific heat at of Then The hydrodynam 1 mm. The therm (A) 0.001 mm (C) 1 mm	over a heated plate, the fole Viscosity = 0.001H constant pressure = 1 kJ/k rmal conductivity = 1W/m ic boundary layer thickness hal boundary layer thickness (B (D	lowing fluid properties Pa-s; g.K; I - K s at a specified location ss at the same location ) 0.01 mm 0 1000 mm	s are known on on the plate is n is
SOL 1.14	Option (C) is correct. Given : $\mu = 0.001 \text{ Pa-s}$ , $c_p = 1 \text{ kJ/kg K}$ , $k = 1 \text{ W/m K}$ The prandtl Number is given by, $\Pr = \frac{\mu c_p}{k} = \frac{0.001 \times 1 \times 10^3}{1} = 1$			
	And Given,	$\frac{\delta}{\delta_t} = \frac{\text{hydrodynamic bond}}{\text{Thermal boundar}}$ $\frac{\delta}{\delta} = 1 \text{ m}$ $\frac{\delta}{\delta_t} = (1)^{1/3} = 1$ $\delta = \delta_t = 1 \text{ mm}$	$\frac{\text{ary layer thickness}}{\text{y layer thickness}} = ($	$(Pr)^{1/3}$
	Hence, thermal b	oundary layer thickness at	same location is 1 mn	a.
MCQ 1.15	For the continuity	v equation given by $\nabla \cdot V$	= 0 to be valid, where	V is the velocity

GATE ME 2008 vector, which one of the following is a necessary condition ?

(C) inviscid flow

(D) incompressible flow

Option (D) is correct.

The continuity equation in three dimension is given by,  

$$\frac{\partial}{\partial x}(\rho u) + \frac{\partial}{\partial y}(\rho v) + \frac{\partial}{\partial z}(\rho w) = 0$$

For incompressible flow  $\rho$ =Constant

$$\rho \left[ \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right] = 0$$
$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$
$$\nabla \cdot V = 0$$

So, the above equation represents the incompressible flow.

Which one of the following is NOT a necessary assumption for the air-standard **MCQ 1.16** Otto cycle ? GATE ME 2008 ONE MARK

- (A) All processes are both internally as well as externally reversible.
- (B) Intake and exhaust processes are constant volume heat rejection processes.
- (C) The combustion process is a constant volume heat addition process.
- (D) The working fluid is an ideal gas with constant specific heats.

**SOL 1.16** Option (B) is correct.



Assumptions of air standard otto cycle :-

- (A) All processes are both internally as well as externally reversible.
- (B) Air behaves as ideal gas
- (C) Specific heats remains constant  $(c_p \& c_v)$
- (D) Intake process is constant volume heat addition process & exhaust process is constant volume heat rejection process.

Intake process is a constant volume heat addition process, From the given options, option (2) is incorrect.

GATE ME 2008 In an M/M/1 queuing system, the number of arrivals in an interval of length T is a ONE MARK

**SOL 1.15** 

Poisson random variable (i.e. the probability of there being arrivals in an interval

The probability density function f(t) of the inter-arrival time is given by

(A) 
$$\lambda^2 (e^{-\lambda^2 t})$$
 (B)  $\frac{e^{-\lambda^2 t}}{\lambda^2}$   
(C)  $\lambda e^{-\lambda t}$  (D)  $\frac{e^{-\lambda t}}{\lambda}$ 

**SOL 1.17** Option (C) is correct.

The most common distribution found in queuing problems is poisson distribution. This is used in single-channel queuing problems for random arrivals where the service time is exponentially distributed.

Probability of n arrivals in time t

of length T is  $\frac{e^{-\lambda T}(\lambda T)^n}{n!}$ ).

$$P = \frac{(\lambda T)^n \cdot e^{-\lambda T}}{n!} \qquad \text{where } n = 0, 1, 2.....$$

So, Probability density function of inter arrival time (time interval between two consecutive arrivals)

$$f(t) = \lambda \cdot e^{-\lambda t}$$

MCQ 1.18A set of 5 jobs is to be processed on a single machine. The processing time (in days)GATE ME 2008<br/>ONE MARKis given in the table below. The holding cost for each job is Rs. K per day.

Job	Processing time
Р	5
Q	2
R	3
S	2
Т	1

A schedule that minimizes the total inventory cost is (A) T-S-Q-R-P (B) P-R-S-Q-T

(C	) $T$ - $R$ - $S$ - $Q$ - $P$	(Γ	D)	P-Q-R-S-T

**SOL 1.18** Option (A) is correct.

Total inventory cost will be minimum, when the holding cost is minimum. Now, from the Johnson's algorithm, holding cost will be minimum, when we process the least time consuming job first. From this next job can be started as soon as possible.

Now, arrange the jobs in the manner of least processing time.

T-S-Q-R-P or T-Q-S-R-P (because job Q and S have same processing time).

GATE ME 2008 For generating a Coon's surface we require ONE MARK

Brought to you by: Nodia and Company PUBLISHING FOR GATE

Page 11	ME GATE-08	www.gatehelp.com	
	<ul> <li>(A) a set of grid points on the surface</li> <li>(B) a set of grid control points</li> <li>(C) four bounding curves defining the surface</li> <li>(D) two bounding curves and a set of grid of grid and a set of grid of grid and a set of gr</li></ul>	ace control points	
SOL 1.19	Option (C) is correct Coon's surface is obtained by blending four boundary curves. The main advantage of Coon's surface is its ability to fit a smooth surface through digitized points in space such as those used in reverse engineering.		
MCQ 1.20 GATE ME 2008 ONE MARK	Internal gear cutting operation can be perfected.(A) milling(C) shaping with pinion cutter	ormed by 3) shaping with rack cutter 0) hobbing	
SOL 1.20	Option (C) is correct. Internal gear cutting operation can be perfected the case of 'rotating pinion type cutter', such this type is more productive and so common	ormed by shaping with pinion cutter. In h an indexing is not required, therefore, on.	
MCQ 1.21 GATE ME 2008 TWO MARK	Consider the shaded triangular region P sh gale herefore back and a bac	own in the figure. What is $\iint_{P} xy dx dy$ ?	
	$(A) \frac{1}{6} \tag{E}$	3) $\frac{2}{9}$	
SOL 1.21	(C) $\frac{7}{16}$ (D) Option (A) is correct. Given :	D) 1	
	b = 1 $P$ $a = 2$		
	We know that the equation of line in interc	cept form is given by	

#### www.gatehelp.com

$$\frac{x}{2} + \frac{y}{1} = 1 \qquad \qquad \frac{x}{a} + \frac{y}{b} = 1$$

$$x + 2y = 2 \Rightarrow x = 2(1 - y)$$

The limit of x is between 0 to x = 2(1 - y) & y is 0 to 1,

Now 
$$\iint_{p} xy dx dy = \int_{y=0}^{y=1} \int_{x=0}^{2(1-y)} xy dx dy$$
$$= \int_{y=0}^{y=1} \left[\frac{x^{2}}{2}\right]_{0}^{2(1-y)} y dy$$
$$= \int_{y=0}^{y=1} y \left[\frac{4(1-y)^{2}}{2} - 0\right] dy$$
$$= \int_{y=0}^{y=1} 2y(1+y^{2}-2y) dy = \int_{y=0}^{y=1} 2(y+y^{3}-2y^{2}) dy$$

Again Integrating and substitute the limits, we get

$$= 2\left[\frac{y^2}{2} + \frac{y^4}{4} - \frac{2y^3}{3}\right]_0^1 = 2\left[\frac{1}{2} + \frac{1}{4} - \frac{2}{3} - 0\right]$$
$$= 2\left[\frac{6+3-8}{12}\right] = \frac{2}{12} = \frac{1}{6}$$

MCQ 1.22The directional derivative of the scalar function  $f(x, y, z) = x^2 + 2y^2 + z$  at the pointGATE ME 2008P = (1, 1, 2) in the direction of the vector  $\boldsymbol{a} = 3\boldsymbol{i} - 4\boldsymbol{j}$  is

(A) 
$$-4$$
  
(C)  $-1$  (B)  $-2$   
(D)  $1$ 

**SOL 1.22** Option (B) is correct.

We know that direction derivative of a function f along a vector P is given by

where

grad 
$$f = \left(\frac{\partial f}{\partial x}\mathbf{i} + \frac{\partial f}{\partial y}\mathbf{j} + \frac{\partial f}{\partial z}\mathbf{k}\right)$$

 $a = \operatorname{grad} f \cdot \frac{a}{|a|}$ 

&

$$f(x, y, z) = x^{2} + 2y^{2} + z, \quad a = 3i - 4j$$
  
$$a = \operatorname{grad} (x^{2} + 2y^{2} + z) \cdot \frac{3i - 4j}{\sqrt{(3)^{2} + (-4)^{2}}}$$
  
$$= (2xi + 4yj + k) \cdot \frac{(3i - 4j)}{\sqrt{25}} = \frac{6x - 16y}{5}$$

At point P(1, 1, 2) the direction derivative is

$$a = \frac{6 \times 1 - 16 \times 1}{5} = -\frac{10}{5} = -2$$

**MCQ 1.23** For what value of a, if any will the following system of equation in x, y and z have a solution ? TWO MARK

$$2x + 3y = 4$$
$$x + y + z = 4$$

3x + 2y - z = a(A) Any real number (B) 0(C) 1 (D) There is no such value **SOL 1.23** Option (B) is correct. Given : 2x + 3y = 4x + y + z = 4x + 2y - z = aIt is a set of non-homogenous equation, so the augmented matrix of this system is  $[A:B] = \begin{bmatrix} 2 & 3 & 0 & : & 4 \\ 1 & 1 & 1 & : & 4 \\ 1 & 2 & -1 & : & a \end{bmatrix}$ Applying row operations,  $R_3 \rightarrow R_3 + R_2, R_2 \rightarrow 2R_2 - R_1$  $[A:B] = \begin{vmatrix} 2 & 3 & 0 & \vdots & 4 \\ 0 & -1 & 2 & \vdots & 4 \\ 2 & 3 & 0 & \vdots & 4 + a \end{vmatrix}$ Again applying row operation  $\begin{bmatrix} A:B \end{bmatrix} = \begin{bmatrix} 2 & 3 & 0 & 1 & 4 \\ 0 & -1 & 2 & 1 & 4 \\ 0 & 0 & 0 & 1 & a \end{bmatrix}$ So, for a unique solution of the system of equations, it must have the condition  $\rho[A:B] = \rho[A]$ So, when putting a = 0 $\rho[A:B] = \rho[A]$ We get Which of the following integrals is unbounded ? MCQ 1.24 (A)  $\int_0^{\pi/4} \tan x dx$ GATE ME 2008 (B)  $\int_{0}^{\infty} \frac{1}{x^{2} + 1} dx$ TWO MARK (D)  $\int_{0}^{1} \frac{1}{1-x} dx$ (C)  $\int_{0}^{\infty} x e^{-x} dx$ **SOL 1.24** Option (D) is correct. Here we check all the four options for unbounded condition.  $\int_{0}^{\pi/4} \tan x \, dx = \left[ \log |\sec x| \right]_{0}^{\pi/4} = \left[ \log |\sec \frac{\pi}{4}| - \log |\sec 0| \right]$  $(\mathbf{A})$  $=\log\sqrt{2} - \log 1 = \log\sqrt{2}$  $\int_0^\infty \frac{1}{x^2 + 1} \, dx = \left[ \tan^{-1} x \right]_0^\infty$ (B) $= \tan^{-1} \infty - \tan^{-1}(0) = \frac{\pi}{2} - 0 = \frac{\pi}{2}$ 

(C) 
$$\int_{0}^{\infty} x e^{-x} dx$$
  
Let 
$$I = \int_{0}^{\infty} x e^{-x} dx$$
$$= x \int_{0}^{\infty} e^{-x} dx - \int_{0}^{\infty} \left[ \frac{d}{dx}(x) \int e^{-x} dx \right] dx$$
$$= \left[ -x e^{-x} \right]_{0}^{\infty} + \int_{0}^{\infty} e^{-x} dx$$
$$= \left[ -x e^{-x} - e^{-x} \right]_{0}^{\infty} = \left[ -e^{-x} (x+1) \right]_{0}^{\infty}$$
$$= -\left[ 0 - 1 \right] = 1$$
(D) 
$$\int_{0}^{1} \frac{1}{1-x} dx = -\int_{0}^{1} \frac{1}{x-1} dx = -\left[ \log (x-1) \right]_{0}^{1}$$
$$-\left[ \log 0 - \log (-1) \right]$$

both log 0 & log (-1) undefined so it is unbounded.

The integral  $\oint f(z) dz$  evaluated around the unit circle on the complex plane for **MCQ 1.25**  $f(z) = \frac{\cos z}{z}$  is GATE ME 2008 TWO MARK

(A) 
$$2\pi i$$
  
(C)  $-2\pi i$   
Sol 1.25 Option (A) is correct.  
Let  $I = \oint f(z) dz \& f(z) = \frac{\cos z}{z}$   
Then  $I = \oint \frac{\cos z}{z} dz = \oint \frac{\cos z}{|z-0|} dz$  ...(i)  
Given that  $|z| = 1$  for unit circle  
From the Cauchy Integral formula  
 $\oint \frac{f(z)}{z-a} dz = 2\pi i f(a)$  ...(ii)  
Compare equation (i) & (ii), we can say that,  
 $a = 0 \& f(z) = \cos z$   
Or,  $f(a) = f(0) = \cos 0 = 1$   
Now from equation (ii) we get  
 $\oint \frac{f(z)}{z-0} dz = 2\pi i \times 1 = 2\pi i$   $a = 0$ 

**MCQ 1.26** The length of the curve  $y = \frac{2}{3}x^{3/2}$  between x = 0 and x = 1 is GATE ME 2008 (A) 0.27 (B) 0.67 TWO MARK (C) 1 (D) 1.22

**SOL 1.26** Option (D) is correct. 0

#### www.gatehelp.com

Given

$$y = \frac{2}{3}x^{3/2}$$
 ...(i)

We know that the length of curve is given by  $\int_{x_1}^{x_2} \left\{ \sqrt{\left(\frac{dy}{dx}\right)^2 + 1} \right\} dx$  ...(ii)

Differentiate equation(i) w.r.t. x

$$\frac{dy}{dx} = \frac{2}{3} \times \frac{3}{2} x^{\frac{3}{2}-1} = x^{1/2} = \sqrt{x}$$

Substitute the limit  $x_1 = 0$  to  $x_2 = 1 \& \frac{dy}{dx}$  in equation (ii), we get

$$\mathcal{L} = \int_0^1 \left( \sqrt{(\sqrt{x})^2 + 1} \right) dx = \int_0^1 \sqrt{x + 1} \, dx$$

Integrating the equation and put the limits

$$= \left[\frac{2}{3}(x+1)^{3/2}\right]_{0}^{1}$$
$$\mathcal{L} = 1.22$$

**MCQ 1.27** The eigen vector of the matrix  $\begin{bmatrix} 1 & 2 \\ 0 & 2 \end{bmatrix}$  are written in the form  $\begin{bmatrix} 1 \\ a \end{bmatrix}$  and  $\begin{bmatrix} 1 \\ b \end{bmatrix}$ . What is TWO MARK a + b?

(A) 0  
(C) 1  
Option (B) is correct
$$\begin{array}{c}
\textbf{g.ate} (B) \frac{1}{2} \\
\textbf{(D) 2} \\
\textbf{holn}
\end{array}$$

**SOL 1.27** Option (B) is correct.

Let

And  $\lambda_1 \& \lambda_2$  is the eigen values of the matrix. We know for eigen values characteristic matrix is,

 $A = \begin{bmatrix} 1 & 2 \\ 0 & 2 \end{bmatrix}$ 

$$\begin{vmatrix} A - \lambda I \end{vmatrix} = 0$$

$$\begin{bmatrix} 1 & 2 \\ 0 & 2 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \end{vmatrix} = 0$$

$$\begin{vmatrix} (1 - \lambda) & 2 \\ 0 & (2 - \lambda) \end{vmatrix} = 0 \qquad \dots(i)$$

$$(1 - \lambda)(2 - \lambda) = 0$$

$$\lambda = 1 \& 2$$

ուր

So, Eigen vector corresponding to the  $\lambda = 1$  is,

$$\begin{bmatrix} 0 & 2 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ a \end{bmatrix} = 0$$
$$2a + a = 0 \Rightarrow a = 0$$
Again for  $\lambda = 2$ 
$$\begin{bmatrix} -1 & 2 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ b \end{bmatrix} = 0$$

Brought to you by: Nodia and Company PUBLISHING FOR GATE

Visit us at: www.nodia.co.in

$$-1+2b=0 \qquad b=\frac{1}{2}$$
Then sum of  $a \& b \Rightarrow a+b=0+\frac{1}{2}=\frac{1}{2}$ 
MCQ 1.28 Let  $f=y^r$ . What is  $\frac{\partial^2 f}{\partial x \partial y}$  at  $x=2, y=1$ ?
  
(A) 0 (B)  $\ln 2$ 
(C) 1 (C) is correct.
  
Given  $f(x,y)=y^r$ 
First partially differentiate the function w.r.t.  $y$ 
 $\frac{\partial}{\partial y} = xy^{r-1}$ 
Again differentiate. it w.r.t.  $x$ 
 $\frac{\partial^2 f}{\partial x \partial y} = y^{r-1}(1)$ 
At:  $x=2, y=1$ 
  
MCQ 1.29 It is given that  $y''+2y'+y=0, y(0)=0$  by  $y(1)=0$ . What is  $y(0.5)$ ?
  
Given  $(y'+2y'+y)=0$ 
(C) 0.62 (D) 1.13
  
Sol 1.29 Option (A) is correct.
  
Given:  $y''+2y'+y=0$ 
( $D^2+2D+1$ )  $y=0$ 
where  $D=d/dx$ 
The auxiliary equation is
 $m^2+2m+1=0$ 
( $m+1$ )<sup>2</sup> = 0,  $m=-1,-1$ 
The roots of auxiliary equation are equal & hence the general solution of the given differential equation is,
 $y = (C_1+C_2x)e^{w_1x} = (C_1+C_2x)e^{-x}$ ...(i)
  
Given  $y(0) = 0$  at  $x=0$ ,  $y=0$ 
  
Substitute in equation (i), we get
 $0 = (C_1+C_2\times 0)e^{-\theta}$ 
 $C_1+C_2(1)e^{-1} = [C_1+C_2]\frac{1}{e}$ 





The strain energy stored in the beam with flexural rigidity EI and loaded as shown in the figure is



From equation (i),

Visit us at: www.nodia.co.in

...(i)

$$R_A = 2P - P = P$$

With the help of  $R_A \& R_B$ , we have to make the Bending moment diagram of the given beam. From this B.M.D, at section AC & BD Bending moment varying with distance but at section CD, it is constant

We know that,

Strain energy 
$$U = \int \frac{M^2}{2EI} dx$$

Where M is the bending moment of beam. Total strain energy is given by

$$U = \underbrace{\int_{0}^{L} \frac{(Px)^{2} dx}{2EI}}_{\text{{for section } AC}} + \underbrace{\frac{(PL)^{2} 2L}{2EI}}_{\text{{for section } CD}} + \underbrace{\int_{0}^{L} \frac{(Px)^{2} dx}{2EI}}_{\text{{for section } BD}}$$
$$= 2\int_{0}^{L} \frac{(Px)^{2} dx}{2EI} + \frac{P^{2}L^{3}}{EI} = \frac{P^{2}}{EI} \int_{0}^{L} x^{2} dx + \frac{P^{2}L^{3}}{EI}$$

On integrating above equation, we get

$$U = \frac{P^2}{EI} \left[\frac{x^3}{3}\right]_0^L + \frac{P^2 L}{EI}$$

On substituting the limits, we get

$$U = \frac{P^2 L^3}{3EI} + \frac{P^2 L^3}{EI} = \frac{4P^2 L^3}{3EI}$$

For the component loaded with a force F as shown in the figure, the axial stress **MCQ 1.31** at the corner point P is GATE ME 2008 hel TWO MARK





Option (D) is correct. Here corner point P is fixed.

(B) 
$$\frac{3(3L+b)}{4b^3}$$
  
(D)  $\frac{F(3L-2b)}{4b^3}$ 

At point P double stresses are acting, one is due to bending & other stress is due to the direct Load.

So, bending stress, (From the bending equation)

$$\sigma_b = \frac{M}{I} y$$

Distance from the neutral axis to the external fibre  $y = \frac{2b}{2} = b$ ,  $\sigma_b = \frac{F(L-b)}{\frac{(2b)^4}{12}} \times b$  For squ For square section  $I = \frac{b^4}{12}$ 

$$\sigma_b = rac{12F(L-b)}{16b^3} = rac{3F(L-b)}{4b^3}$$

& Direct stress,

$$\sigma_d = \frac{F}{(2b)^2} = \frac{F}{4b^2} = \frac{F}{4b^2} \times \frac{b}{b} = \frac{Fb}{4b^3}$$

Total axial stress at the corner point P is,

$$\sigma = \sigma_b + \sigma_d = rac{3F(L-b)}{4b^3} + rac{Fb}{4b^3}$$
 $\sigma = rac{F(3L-2b)}{4b^3}$ 

A solid circular shaft of diameter 100 mm is subjected to an axial stress of 50 **MCQ 1.32** MPa. It is further subjected to a torque of 10 kNm. The maximum principal stress GATE ME 2008 experienced on the shaft is closest to TWO MARK

(A) 41 MPa	(B) 82 MPa
(C) 164 MPa	(D) 204 MPa

**SOL 1.32** 

Option (B) is correct.



 $\tau_{xy} = \frac{T}{I} \times r$ 

The shaft is subjected to a torque of 10 kN-m and due to this shear stress is developed in the shaft,

From Torsional equation

$$\tau_{xy} = \frac{10 \times 10^3}{\frac{\pi}{32}d^4} \times \frac{d}{2} = \frac{16 \times 10 \times 10^3}{\pi d^3}$$
$$\tau_{xy} = \frac{16 \times 10^4}{3.14 \times (10^{-1})^3} = \frac{160}{3.14} = 50.95 \,\text{MPa}$$

Maximum principal stress,

Brought to you by: Nodia and Company PUBLISHING FOR GATE **ME GATE-08** 

www.gatehelp.com

$$\sigma_1 = \frac{\sigma_x + \sigma_y}{2} + \frac{1}{2}\sqrt{(\sigma_x - \sigma_y)^2 + 4\tau_{xy}^2}$$

Substitute the values, we get

$$\sigma_{1} = \frac{50}{2} + \frac{1}{2}\sqrt{(50)^{2} + 4 \times (50.95)^{2}}$$
$$\sigma_{1} = 25 + \frac{1}{2}\sqrt{12883.61} = 25 + \frac{113.50}{2}$$
$$\sigma_{1} = 25 + 56.75 = 81.75 \text{ MPa} \approx 82 \text{ MPa}$$

**MCQ 1.33** A circular disk of radius R rolls without slipping at a velocity V. The magnitude of the velocity at point P (see figure) is





When disc rolling along a straight path, without slipping. The centre of the wheel O moves with some linear velocity and each particle on the wheel rotates with some angular velocity.



Thus, the motion of any particular on the periphery of the wheel is a combination of linear and angular velocity.

Let wheel rotates with angular velocity= $\omega$  rad/sec.

So, 
$$\omega = \frac{V}{R}$$
 ....(i)

Velocity at point P is

$$V_P = \omega \times PQ \qquad \qquad \dots (ii)$$

Visit us at: www.nodia.co.in

Page 21

ONE MARK

**ME GATE-08** 

From triangle 
$$OPQ$$
  $PQ \sqrt{(OQ)^2 + (OP)^2 - 2OQ \times OP} \times \cos(\angle POQ)$   
 $PQ = \sqrt{(R)^2 + (R)^2 - 2RR\cos 120^\circ}$   
 $PQ = \sqrt{(R)^2 + (R)^2 + (R)^2}$   
 $PQ = \sqrt{3} R$  ...(iii)  
From equation (i), (ii) and (iii)  
 $V_P = \frac{V}{R} \times \sqrt{3} R$ 

$$V_P = \sqrt{3} V$$

Consider a truss PQR loaded at P with a force F as shown in the figure -**MCQ 1.34** 



**SOL 1.34** Option (B) is correct.

> The forces which are acting on the truss PQR is shown in figure. We draw a perpendicular from the point P, that intersects QR at point S.



PS = QS = aLet  $R_Q \& R_R$  are the reactions acting at point Q & R respectively. Now from the triangle PRS

$$\tan 30^\circ = \frac{PS}{SR}$$

Visit us at: www.nodia.co.in

**ME GATE-08** 

$$SR = \frac{PS}{\tan 30^{\circ}} = \frac{a}{\frac{1}{\sqrt{3}}} = \sqrt{3} \ a = 1.73a$$

Taking the moment about point R,

 $R_Q \times (a+1.73a) = F \times 1.73a$ 

$$R_Q = \frac{1.73 \, a \, \mathrm{F}}{2.73 \, a} = \frac{1.73 \, \mathrm{F}}{2.73} = 0.634 \, \mathrm{F}$$

From equilibrium of the forces, we have

$$R_R + R_Q = F$$
  

$$R_R = F - R_Q = F - 0.634 \text{ F} = 0.366 \text{ F}$$

To find tension in QR we have to use the method of joint at point Q, and  $\Sigma F_y = 0$  $F_{QP} \sin 45^\circ = R_Q$ 

$$F_{QP} = \frac{0.634 \text{ F}}{\frac{1}{\sqrt{2}}} = 0.8966 \text{ F}$$

And,  $\Sigma F_x = 0$ 

$$F_{QP}\cos 45^{\circ} = F_{QR} \ \Rightarrow F_{QR} = 0.8966 \,\mathrm{F} imes rac{1}{\sqrt{2}} = 0.634 \,\mathrm{F} \simeq 0.63 \,\mathrm{F}$$



$k_{1} = 4000 \text{ N/m}$	 $-\underbrace{\mathbf{M}}_{k_2} = 1600 \text{ N/m}$
(A) 8 Hz	(B) 10 Hz
(C) 12 Hz	(D) 14 Hz

**SOL 1.35** Option (B) is correct. Given m = 1.4 kg,  $k_1 = 4000$  N/m,  $k_2 = 1600$  N/m In the given system  $k_1 \& k_2$  are in parallel combination So,  $k_{eq} = k_1 + k_2 = 4000 + 1600 = 5600$  N/m Natural frequency of spring mass system is given by,  $f_n = \frac{1}{2\pi} \sqrt{\frac{k_{eq}}{m}} = \frac{1}{2\pi} \sqrt{\frac{5600}{1.4}}$ 

$$=\frac{1}{2\pi} \times 63.245 = 10.07 \simeq 10 \,\mathrm{Hz}$$

**MCQ 1.36** The rod PQ of length L and with flexural rigidity EI is hinged at both ends. For what minimum force F is it expected to buckle ?







**6** Option (B) is correct.



We know that according to Euler's theory, the crippling or buckling load  $(W_{cr})$  under various end conditions is represented by the general equation,

$$W_{cr} = \frac{C\pi^2 EI}{L^2} \qquad \dots (i)$$

Where

L =length of column

C =Constant, representing the end conditions of the column.

Here both ends are hinged,

C = 1

From equation (i),

$$W_{cr} = rac{\pi^2 EI}{L^2}$$

Minimum force F required is  $W_{cr} = F \cos 45^{\circ}$ 

$$F = \frac{W_{cr}}{\cos 45^\circ} = \frac{\sqrt{2} \,\pi^2 EI}{L^2}$$

**MCQ 1.37** In a cam design, the rise motion is given by a simple harmonic motion  $\begin{array}{l} \text{GATE ME 2008} \\ \text{TWO MARK} \end{array} \quad (SHM) \, s = \frac{h}{2} \Big( 1 - \cos \frac{\pi \theta}{\beta} \Big) \text{ where } h \text{ is total rise, } \theta \text{ is camshaft angle, } \beta \text{ is the total} \\ \text{ angle of the rise interval . The jerk is given by} \end{array}$ 

(A) 
$$\frac{h}{2} \left( 1 - \cos \frac{\pi \theta}{\beta} \right)$$
 (B)  $\frac{\pi h}{\beta 2} \sin \left( \frac{\pi \theta}{\beta} \right)$ 

$$\frac{1}{\beta}\frac{1}{2}\sin\left(\frac{1}{\beta}\right)$$

Brought to you by: Nodia and Company PUBLISHING FOR GATE Visit us at: www.nodia.co.in

www.gatehelp.com

$$(C) \frac{\pi^{2}}{\beta^{2}} \frac{h}{2} \cos\left(\frac{\pi\theta}{\beta}\right) \qquad (D) -\frac{\pi^{3}}{\beta^{3}} \frac{h}{2} \sin\left(\frac{\pi\theta}{\beta}\right)$$
**SOL 1.37** Option (D) is correct.  
Jerk is given by triple differentiation of s w.r.t. t,  

$$Jerk = \frac{d^{3}s}{dt^{3}}$$
Given
$$s = \frac{h}{2} \left(1 - \cos\frac{\pi\theta}{\beta}\right) = \frac{h}{2} \left[1 - \cos\frac{\pi(\omega t)}{\beta}\right] \qquad \theta = \omega t$$
Differentiating above equation w.r.t. t, we get  

$$\frac{ds}{dt} = \frac{h}{2} \left[-\frac{\pi\omega}{\beta} \left\{-\sin\frac{\pi(\omega t)}{\beta}\right\}\right]$$
Again Differentiating w.r.t. t,  

$$\frac{d^{2}s}{dt^{2}} = \frac{h}{2} \frac{\pi^{2}\omega^{2}}{\beta^{2}} \left[\cos\frac{\pi(\omega t)}{\beta}\right]$$
Again Differentiating w.r.t. t,  

$$\frac{d^{3}s}{dt^{3}} = -\frac{h}{2} \frac{\pi^{3}\omega^{3}}{\beta^{3}} \sin\frac{\pi\theta}{\beta}$$
Let  $\omega = 1 \operatorname{rad/sec}$ 

$$\frac{d^3s}{dt^3} = -\frac{h}{2}\frac{\pi^3}{\beta^3}\sin\left(\frac{\pi\theta}{\beta}\right)\mathbf{C}$$

**MCQ 1.38** A uniform rigid rod of mass m = 1 kg and length L = 1 m is hinged at its centre and laterally supported at one end by a spring of spring constant k = 300 N/m. The natural frequency  $\omega_n$  in rad/s is

(A) 10	(B) $20$
(C) 30	(D) 40

**SOL 1.38** Option (C) is correct.



Given m = 1 kg, L = 1 m, k = 300 N/m

We have to turn the rigid rod at an angle  $\theta$  about its hinged point, then rod moves upward at a distance x and also deflect in the opposite direction with the same

www.gatehelp.com

...(ii)

amount. Let  $\theta$  is very very small and take  $\tan \theta \simeq \theta$ 

From 
$$\Delta AOB$$
,  $\theta = \frac{x}{\frac{L}{2}} \Rightarrow x = \frac{L}{2}\theta$  ...(i)

 $\theta = \overset{2}{\omega t} \Rightarrow \dot{\theta} = \omega$ 

By using the principal of energy conservation,

$$\frac{1}{2}I\omega^2 + \frac{1}{2}kx^2 = \text{Constant}$$

$$\frac{1}{2}I\dot{\theta}^2 + \frac{1}{2}k\left(\frac{L}{2}\theta\right)^2 = c$$
From equation (i) and (ii)
$$\frac{1}{2}I\dot{\theta}^2 + \frac{1}{8}L^2k\theta^2 = c$$

On differentiating w.r.t. t, we get

$$\frac{1}{2}I \times 2\dot{\theta}\ddot{\theta} + \frac{kL^2}{8} \times 2\theta\dot{\theta} = 0 \qquad \dots (\text{iii})$$

For a rigid rod of length L & mass m, hinged at its centre, the moment of inertia,

 $I = \frac{mL^2}{12}$ 

Substitute I in equation (iii), we get  

$$\frac{1}{2} \times \frac{mL^2}{12} \times 2\dot{\theta}\ddot{\theta} + \frac{kL^2}{4}\theta\dot{\theta} = 0$$

$$\ddot{\theta} + \frac{3k}{m}\theta = 0$$
...(iv)

Compare equation (iv) with the general equation,

$$\ddot{ heta} + \omega_n^2 heta = 0$$
  
 $\omega^2 - \frac{3k}{2}$ 

So, we have

$$\omega_n = m \ \omega_n = \sqrt{rac{3k}{m}} = \sqrt{rac{3 imes 300}{1}} = 30 \ {
m rad/sec} \ .$$

**MCQ 1.39** GATE ME 2008 TWO MARK

A compression spring is made of music wire of 2 mm diameter having a shear strength and shear modulus of 800 MPa and 80 GPa respectively. The mean coil diameter is 20 mm, free length is 40 mm and the number of active coils is 10. If the mean coil diameter is reduced to 10 mm, the stiffness of the spring is approximately (A) decreased by 8 times

- (B) decreased by 2 times
- (C) increased by 2 times
- (D) increased by 8 times

**SOL 1.39** Option (D) is correct.

We know that deflection in a compression spring is given by

$$\delta = \frac{64PR^3n}{d^4G} = \frac{8PD^3n}{d^4G}$$

Where

n = number of active coils D = Mean coil Diameter

d = Music wire Diameter

&

And

$$k = \frac{P}{\delta} = \frac{d^4 G}{8D^3 n}$$
$$k \propto \frac{1}{D^3}$$

Given that mean coil diameter is reduced to 10 mm.

 $\operatorname{So},$ 

 $D_1 = 20 \text{ mm}$  $D_2 = 20 - 10 = 10 \text{ mm}$ 

&

$$\frac{k_2}{k_1} = \left(\frac{D_1}{D_2}\right)^3 = \left(\frac{20}{10}\right)^3 = 8$$
  
$$k_2 = 8k_1$$

So, stiffness is increased by 8 times.



then total frictional torque acting on the friction surface or on the clutch is given by,

$$T = 2\pi\mu p \left[ \frac{(r_1)^3 - (r_2)^3}{3} \right]$$
  
=  $\frac{2}{3} \times 3.14 \times 0.4 \times 2 \times 10^6 [(50)^3 - (20)^3] \times 10^{-9}$   
= 195.39 N-m  $\simeq$  196 N-m

MCQ 1.42A spur gear has a module of 3 mm, number of teeth 16, a face width of 36 mm and<br/>a pressure angle of 20°. It is transmitting a power of 3 kW at 20 rev/s. Taking a<br/>velocity factor of 1.5 and a form factor of 0.3, the stress in the gear tooth is about.<br/>(A) 32 MPa(A) 32 MPa(B) 46 MPa

SOL 1.42 Option (B) is correct. Given : m = 3 mm, Z = 16, b = 36 mm,  $\phi = 20^{\circ}$ , P = 3 kW $N = 20 \text{ rev}/\text{sec} = 20 \times 60 \text{ rpm} = 1200 \text{ rpm}, C_v = 1.5, y = 0.3$  $m = \frac{D}{Z}$ Module,  $D = m \times Z = 3 \times 16 = 48 \text{ mm}$  $P = \frac{2\pi NT}{60}$ Power.  $T = \frac{60P}{2\pi N} = \frac{60 \times 3 \times 10^3}{2 \times 3.14 \times 1200}$  $= 23.88 \, \mathrm{N\text{-}m} \, = 23.88 \times 10^3 \, \mathrm{N\text{-}mm}$ Tangential load,  $W_T = \frac{T}{R} = \frac{2T}{D} = \frac{2 \times 23.88 \times 10^3}{48} = 995 \text{ N}$ From the lewis equation Bending stress (Beam strength of Gear teeth)  $\sigma_b = \frac{W_T P_d}{hu}$  $\sigma_b = \frac{W_T}{bum}$  $\left[P_d = \frac{\pi}{P_C} = \frac{\pi}{\pi m} = \frac{1}{m}\right]$  $=\frac{995}{36\times 10^{-3}\times 0.3\times 3\times 10^{-3}}$  $\sigma_b = \frac{995}{3.24 \times 10^{-5}} = 30.70 \times 10^6 \,\mathrm{Pa} = 30.70 \,\mathrm{MPa}$ Permissible working stress  $\sigma_W = \sigma_h \times C_v$  $= 30.70 \times 1.5 = 46.06 \text{ MPa} \cong 46 \text{ MPa}$ 

**MCQ 1.43** Match the type of gears with their most appropriate description.

GATE ME 2008 TWO MARK **Type of gear** P. Helical

- Q. Spiral Bevel
- C. Hypoid
- S. Rack and pinion

### Description

- 1. Axes non parallel and non intersecting
- 2. Axes parallel and teeth are inclined to the axis
- 3. Axes parallel and teeth are parallel to the axis
- 4. Axes are perpendicular and intersecting, and teeth are inclined to the axis.
- 5. Axes are perpendicular and used for large speed reduction
- 6. Axes parallel and one of the gears has infinite radius
- (A) P-2, Q-4, R-1, S-6 (B) P-1, Q-4, R-5, S-6
- (C) P-2, Q-6, R-4, S-2 (D) P-6, Q-3, R-1, S-5

### **SOL 1.43** Option (A) is correct.

Р.

**Types of Gear** 

### Description

- Helical **2.** Axes parallel and teeth are inclined to the axis
- Q. Spiral Bevel4. Axes are perpendicular and intersecting, and teeth are inclined to the axis
- **R.** Hypoid **1.** Axes non parallel and non-intersecting
- **S.** Rack and pinion **6.** Axes are parallel and one of the gear has infinite radius So, correct pairs are P-2, Q-4, R-1, S-6

MCQ 1.44A gas expands in a frictionless piston-cylinder arrangement. The expansion process<br/>is very slow, and is resisted by an ambient pressure of 100 kPa. During the expansion<br/>process, the pressure of the system (gas) remains constant at 300 kPa. The change<br/>in volume of the gas is  $0.01 \text{ m}^3$ . The maximum amount of work that could be<br/>utilized from the above process is<br/>(A) 0 kJ<br/>(C) 2 kJ(B) 1 kJ<br/>(D) 3 kJSOL 1.44Option (C) is correct.<br/>Given :  $p_a = 100 \text{ kPa}$ ,  $p_s = 300 \text{ kPa}$ ,  $\Delta \nu = 0.01 \text{ m}^3$ 

Net pressure work on the system,

 $p = p_s - p_a = 300 - 100 = 200 \text{ kPa}$ 

Brought to you by: Nodia and Company PUBLISHING FOR GATE







$$rac{\partial p_{t}}{\partial p_{c}}(t_{h1}-t_{h2})=rac{m_{c}}{\dot{m}_{h}}(t_{c2}-t_{c1}) 
onumber \ 2(t_{h1}-t_{h2})=2(t_{c2}-t_{c1}) 
onumber \ t_{h1}-t_{c2}=t_{h2}-t_{c1} 
onumber \ heta_{1}= heta_{2}$$

Brought to you by: Nodia and Company PUBLISHING FOR GATE Visit us at: www.nodia.co.in

...(iii)

**ME GATE-08** 

#### www.gatehelp.com

And

$$\theta_m = \frac{\theta_1 - \theta_2}{\ln\left(\frac{\theta_1}{\theta_2}\right)} \qquad \dots (iv)$$

On substituting the equation (iii) in equation (iv), we get undetermined form.

Let 
$$\frac{\theta_1}{\theta_2} = x, \Rightarrow \theta_1 = \theta_2 x$$
 ...(v)

Substitute  $\theta_1$  in equation(iv),

$$\theta_m = \lim_{x \to 1} \frac{\theta_2 x - \theta_2}{\ln\left(\frac{\theta_2 x}{\theta_2}\right)} = \lim_{x \to 1} \frac{\theta_2 (x - 1)}{\ln x} \qquad \dots (\text{vi})$$



From equation(iii)

Now we have to find exit temperature of cold fluid  $(t_{c2})$ ,

So,

 $\theta_m = \theta_1 = t_{h1} - t_{c2}$  $t_{c2} = t_{h1} - \theta_m = 100 - 20 = 80^{\circ} \,\mathrm{C}$ 

A two dimensional fluid element rotates like a rigid body. At a point within the **MCQ 1.46** element, the pressure is 1 unit. Radius of the Mohr's circle, characterizing the state GATE ME 2008 TWO MARK of stress at that point, is \_\_\_\_\_

**SOL 1.46** Option (B) is correct.

Pressure will remain uniform in all directions. So, hydrostatic load acts in all directions on the fluid element and Mohr's circle becomes a point on  $\sigma - \tau$  axis and  $\sigma_x = \sigma_y$  and  $\tau_{xy} = 0$ 

So,  

$$R = \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + (\tau_{xy})^2} = 0$$

$$\downarrow^{\tau}$$
Mohr's Circle

### **MCQ 1.47** GATE ME 2008 TWO MARK

A cyclic device operates between three reservoirs, as shown in the figure. Heat is transferred to/from the cycle device. It is assumed that heat transfer between each thermal reservoir and the cyclic device takes place across negligible temperature difference. Interactions between the cyclic device and the respective thermal reservoirs that are shown in the figure are all in the form of heat transfer.



The cyclic device can be

- (A) a reversible heat engine
- (B) a reversible heat pump or a reversible refrigerator
- (C) an irreversible heat engine
- (D) an irreversible heat pump or an irreversible refrigerator
- **SOL 1.47** Option (A) is correct.

A heat engine cycle is a thermodynamic cycle in which there is a net Heat transfer from higher temperature to a lower temperature device. So it is a Heat Engine. Applying Clausius theorem on the system for checking the reversibility of the cyclic device.

$$\begin{array}{c}
\mathbf{G} \quad \mathbf{d} \quad \mathbf{f}_{R} \quad \frac{dQ}{T} = 0 \\
\frac{Q_{1}}{T_{1}} + \frac{Q_{2}}{T_{2}} \quad \mathbf{f}_{3} \quad \mathbf{f}_{3} \quad \mathbf{f}_{3} \\
\frac{100 \times 10^{3}}{1000} + \frac{50 \times 10^{3}}{500} - \frac{60 \times 10^{3}}{300} = 0
\end{array}$$

100 + 100 - 200 = 0

Here, the cyclic integral of dQ/T is zero. This implies, it is a reversible Heat engine.



- (A) The internal energy of the gas decreases from its initial value, but the enthalpy remains constant
- (B) The internal energy of the gas increases from its initial value, but the enthalpy remains constant
- (C) Both internal energy and enthalpy of the gas remain constant
- (D) Both internal energy and enthalpy of the gas increase

**SOL 1.48** Option (C) is correct.

We know enthalpy,

$$h = U + p\nu$$

U =Internal energy

...(i)

p =Pressure of the room  $\nu =$  Volume of the room

It is given that room is insulated, So there is no interaction of energy (Heat) between system (room) and surrounding (atmosphere).

It means Change in internal Energy dU = 0 & U = Constant

And temperature is also remains constant.

Applying the perfect gas equation,

$$p\nu = nRT$$

$$p\nu = \text{Constant}$$

Therefore, from equation (i)

h = Constant

So this process is a constant internal energy & constant enthalpy process.

### Alternate method

We know that enthalpy,

 $h = U + p\nu$ 

Given that room is insulated, So there is no interaction of Energy (Heat) between system (room) and surrounding (atmosphere).

It means internal Energy dU = 0 & U = constant.

Now flow work  $p\nu$  must also remain constant thus we may conclude that during free expansion process  $p\nu$  i.e. product of pressure and specific volume change in such a way that their product remains constant.

So, it is a constant internal energy & constant enthalpy process.

MCQ 1.49 GATE ME 2008 TWO MARK A rigid, insulated tank is initially evacuated. The tank is connected with a supply line through which air (assumed to be ideal gas with constant specific heats) passes at 1 MPa, 350° C. A valve connected with the supply line is opened and the tank is charged with air until the final pressure inside the tank reaches 1 MPa. The final temperature inside the tank.



(A) is greater than 350°C(B) is less than 350°C

- (C) is equal to  $350^{\circ}$  C
- (D) may be greater than, less than, or equal to,  $350^{\circ}$ C depending on the volume of the tank

**SOL 1.49** Option (A) is correct. Given :  $p_1 = 1$  MPa,  $T_1 = 350^{\circ}$ C = (350 + 273) K = 623 K For air  $\gamma = 1.4$ We know that final temperature ( $T_2$ ) inside the tank is given by,  $T_2 = \gamma T_1 = 1.4 \times 623 = 872.2$  K = 599.2° C  $T_2$  is greater than  $350^{\circ}$  C.

**MCQ 1.50** For the three-dimensional object shown in the figure below, five faces are insulated. **GATE ME 2008 TWO MARK** The sixth face (PQRS), which is not insulated, interacts thermally with the ambient, with a convective heat transfer coefficient of  $10 \text{ W/m}^2 \text{ K}$ . The ambient temperature is  $30^{\circ}$  C. Heat is uniformly generated inside the object at the rate of  $100 \text{ W/m}^3$ . Assuming the face PQRS to be at uniform temperature, its steady state temperature is



**SOL 1.50** 

Option (D) is correct.

Given :  $h = 10 \text{ W/m}^2 \text{ K}$ ,  $T_i = 30^{\circ} \text{ C}$ ,  $q_g = 100 \text{ W/m}^3$ 

Five faces of the object are insulated, So no heat transfer or heat generation by these five faces. Only sixth face (PQRS) interacts with the surrounding & generates heat.

Hence, Heat generated throughout the volume

Q =Rate of heat Generated  $\times$  Volume of object

 $= 100 \times (1 \times 2 \times 2) = 400 \,\mathrm{W}$ 

And heat transfer by convection is given by

$$Q = hA (T_f - T_i)$$
  

$$400 = 10 \times (2 \times 2) (T_f - 30)$$
  

$$T_f = 30 + 10 = 40^{\circ} C$$

Brought to you by: <u>Nodia and Company</u> PUBLISHING FOR GATE at 10 rad/s. The mean diameter of the wheel is 1 m. The jet is split into two equal streams by the bucket, such that each stream is deflected by  $120^{\circ}$  as shown in the figure. Friction in the bucket may be neglected. Magnitude of the torque exerted by the water on the wheel, per unit mass flow rate of the incoming jet, is



Given :  $\rho = 1000 \text{ kg/m}^3$ , V = 10 m/sec,  $\theta = 180 - 120 = 60^\circ$ , R = 0.5 mInitial velocity in the direction of jet = VFinal velocity in the direction of the jet =  $-V\cos\theta$ . Force exerted on the bucket  $F_x = \rho A V [V - (-V\cos\theta)] = \rho A V [1 + \cos\theta] V$   $= Q(1 + \cos\theta) V$  Mass flow rate  $Q = \rho A V$ Torque,  $T_x = F_x \times R = QV(1 + \cos\theta) R$ Torque per unit mass flow rate **ME GATE-08** 

0

$$\frac{T_x}{T_x} = V($$

$$\frac{T_x}{Q} = V(1 + \cos\theta) R = 10(1 + \cos 60^\circ) \times 0.5 = 7.5 \text{ N-m/kg/sec}$$
And
$$F_y = \rho A V(0 - V \sin\theta) = -QV \sin\theta$$
Torque in y-direction
$$T_y = F_y \times R = 0$$
R = 0
Total Torque will be
$$T = \sqrt{T_x^2 + T_y^2} = T_x = 7.5 \text{ N-m/kg/sec}$$

A thermal power plant operates on a regenerative cycle with a single open feed water heater, as shown in the figure. For the state points shown, the specific enthalpies are: $h_1 = 2800 \text{ kJ/kg}$  and  $h_2 = 200 \text{ kJ/kg}$ . The bleed to the feed water heater is 20% of the boiler steam generation rate. The specific enthalpy at state 3 is



Option (A) is correct. **SOL 1.52** 

Given :  $h_1 = 2800 \text{ kJ/kg}, h_2 = 200 \text{ kJ/kg}$ 

From the given diagram of thermal power plant, point 1 is directed by the Boiler to the open feed water heater & point 2 is directed by the pump to the open feed water Heater. The bleed to the feed water heater is 20% of the boiler steam generation i.e. 20% of  $h_1$ 



So,

$$h_3 = 20\%$$
 of  $h_1 + 80\%$  of  $h_2$ 

Brought to you by: Nodia and Company PUBLISHING FOR GATE Visit us at: www.nodia.co.in

 $= 0.2 \times 2800 + 0.8 \times 200 = 720 \text{ kJ/kg}$ 

MCQ 1.53 Moist air at a pressure of 100 kPa is compressed to 500 kPa and then cooled to GATE ME 2008 TWO MARK Moist air at a pressure of 100 kPa is compressed to 500 kPa and then cooled to  $35^{\circ}$ C in an aftercooler. The air at the entry to the aftercooler is unsaturated and becomes just saturated at the exit of the aftercooler. The saturation pressure of water at  $35^{\circ}$ C is 5.628 kPa. The partial pressure of water vapour (in kPa) in the moist air entering the compressor is closest to (A) 0.57 (B) 1.13

$(\mathbf{A})$	0.57	(B)	1.13
(C)	2.26	(D)	4.52

**SOL 1.53** Option (B) is correct.

Given :  $p_1 = 100$  kPa,  $p_2 = 500$  kPa,  $p_{v1} = ?$  $p_{v2} = 5.628$  kPa (Saturated pressure at 35° C) We know that,

Specific humidity

$$W = 0.622 \Big(\frac{p_v}{p - p_v}\Big)$$

For case II :

$$W = 0.622 \left( \frac{5.628}{500 - 5.628} \right) = 7.08 \times 10^{-3} \text{ kg/kg of dry air}$$

For saturated air specific humidity remains same. So, for case (I) :

$$W = 0.622 \left(\frac{p_{v1}}{p_1 - p_{v1}}\right)$$
  
On substituting the values, we get  
$$7.08 \times 10^{-3} = 0.622 \left(\frac{p_{v1}}{100 - p_{v1}}\right)$$
$$11.38 \times 10^{-3} (100 - p_{v1}) = p_{v1}$$
$$1.138 = 1.01138 p_{v1}$$
$$p_{v1} = 1.125 \text{ kPa} \simeq 1.13 \text{ kPa}$$

A hollow enclosure is formed between two infinitely long concentric cylinders of radii 1 m and 2 m, respectively. Radiative heat exchange takes place between the inner surface of the larger cylinder (surface-2) and the outer surface of the smaller cylinder (surface-1). The radiating surfaces are diffuse and the medium in the enclosure is non-participating. The fraction of the thermal radiation leaving the larger surface and striking itself is



Brought to you by: Nodia and Company PUBLISHING FOR GATE

Visit us at: www.nodia.co.in

(A) $0.25$	(B) $0.5$
(C) 0.75	(D) 1

Given :  $D_1 = 1 \text{ m}$ ,  $D_2 = 2 \text{ m}$ 

Hence, the small cylindrical surface (surface 1) cannot see itself and the radiation emitted by this surface strikes on the enclosing surface 2. From the conservation principal (summation rule).

For surface 1,  $F_{12} + F_{11} = 1$  $F_{12} = 1$  $F_{11} = 0$ ...(i)

From the reciprocity theorem

$$A_1 F_{12} = A_2 F_{21}$$
  

$$F_{21} = \frac{A_1}{A_2} = \frac{\pi D_1 L}{\pi D_2 L} = \frac{D_1}{D_2} = \frac{1}{2} = 0.5$$

and from the conservation principal, for surface 2, we have

$$F_{21} + F_{22} = 1$$
  
 $F_{22} = 1 - F_{21} = 1 - 0.5 = 0.5$ 

So, the fraction of the thermal radiation leaves the larger surface & striking itself is  $F_{22} = 0.5$ .

MCQ 1.55 GATE ME 2008 TWO MARK
Air (at atmospheric pressure) at a dry bulb temperature of 40°C and wet bulb temperature of 20°C is humidified in an air washer operating with continuous water recirculation. The wet bulb depression (i.e. the difference between the dry and wet bulb temperature) at the exit is 25% of that at the inlet. The dry bulb temperature at the exit of the air washer is closest to

(A) $10^{\circ}$ C	(B) 20° C
(C) $25^{\circ}$ C	(D) $30^{\circ}$ C

### **SOL 1.55** Option (C) is correct.

Given : At inlet  $t_{DBT} = 40^{\circ}$  C,  $t_{WBT} = 20^{\circ}$  C We know that, wet bulb depression  $= t_{DBT} - t_{WBT} = 40 - 20 = 20^{\circ}$  C And given wet bulb depression at the exit = 25% of wet bulb depression at inlet This process becomes adiabatic saturation and for this process,

So,  
$$t_{WBT(\text{inlet})} = t_{WBT(\text{outlet})}$$
$$t_{DBT(\text{exit})} - 20 = 0.25 \times 20$$
$$t_{DBT(\text{exit})} = 20 + 5 = 25^{\circ} \text{ C}$$

MCQ 1.56 GATE ME 2008 TWO MARK Steady two-dimensional heat conduction takes place in the body shown in the figure below. The normal temperature gradients over surfaces P and Q can be considered to be uniform. The temperature gradient  $\partial T / \partial x$  at surface Q is equal to 10 K/m. Surfaces P and Q are maintained at constant temperature as shown in the figure, while the remaining part of the boundary is insulated. The body has a constant thermal conductivity of 0.1 W/mK. The values of  $\frac{\partial T}{\partial x}$  and  $\frac{\partial T}{\partial y}$  at surface P are



A) 
$$\frac{\partial T}{\partial x} = 20 \text{ K/m}, \quad \frac{\partial T}{\partial y} = 0 \text{ K/m}$$
 (B)  $\frac{\partial T}{\partial x} = 0 \text{ K/m}, \quad \frac{\partial T}{\partial y} = 10 \text{ K/m}$   
C)  $\frac{\partial T}{\partial x} = 10 \text{ K/m}, \quad \frac{\partial T}{\partial y} = 10 \text{ K/m}$  (D)  $\frac{\partial T}{\partial x} = 0 \text{ K/m}, \quad \frac{\partial T}{\partial y} = 20 \text{ K/m}$ 

SOL 1.56 Option (D) is correct.  
Given : 
$$\left(\frac{\partial T}{\partial T}\right) = 10 \text{ K}$$

(

iven : 
$$\left(\frac{\partial T}{\partial x}\right)_Q = 10 \text{ K/m}, (T)_P = (T)_Q, (k)_P = (k)_Q = 0.1 \text{ W/mK}$$

Direction of heat flow is always normal to surface of constant temperature. So, for surface P, **n n n** 

Because,  $Q = -kA\frac{\partial T}{\partial x}$  and  $\partial T$  is the temperature difference for a short perpendicular

distance dx. Let width of both the bodies are unity. From the law of energy conservation,

Heat rate at 
$$P$$
 = Heat rate at  $Q$   
-0.1 × 1 ×  $\left(\frac{\partial T}{\partial y}\right)_P$  = -0.1 × 2 ×  $\left(\frac{\partial T}{\partial x}\right)_Q$ 

Because for P heat flow in y direction & for Q heat flow in x direction

$$\left(\frac{\partial T}{\partial y}\right)_{P} = \frac{0.1 \times 2 \times 10}{0.1} = 20 \,\mathrm{K/m}$$

### MCQ 1.57

GATE ME 2008 TWO MARK In a steady state flow process taking place in a device with a single inlet and a single outlet, the work done per unit mass flow rate is given by  $W = -\int_{\text{inlet}}^{\text{outlet}} \nu dp$ , where  $\nu$  is the specific volume and p is the pressure.

The expression for W given above

- (A) is valid only if the process is both reversible and adiabatic
- (B) is valid only if the process is both reversible and isothermal
- (C) is valid for any reversible process

(D) is incorrect; it must be  $W = \int_{\text{inlet}}^{\text{outlet}} p d\nu$ 

**SOL 1.57** Option (C) is correct. From the first law of thermodynamic, dQ = dU + dWdW = dQ - dU...(i) If the process is complete at the constant pressure & no work is done other than the  $pd\nu$  work. So  $dQ = dU + pd\nu$ At constant pressure  $pd\nu = d(p\nu)$  $(dQ) = dU + d(p\nu) = d(U + p\nu) = (dh)$  $h = U + p\nu$ From equation (i)  $dW = - dh + dQ = - dh + Tds \qquad \qquad ds = dQ/T$ ...(ii) For an reversible process,  $Tds = dh - \nu dp$  $-\nu dp = -dh + Tds$ ...(iii) From equation (ii) & (iii)  $dW = -\nu dp$ On integrating both sides, we get  $W = -\int \nu dp$  It is valid for reversible process. For the standard transportation linear programme with m source and n destinations **MCQ 1.58** GATE ME 2008 and total supply equaling total demand, an optimal solution (lowest cost) with the TWO MARK smallest number of non-zero  $x_{ij}$  values (amounts from source *i* to destination *j*) is desired. The best upper bound for this number is (B) 2(m+n)(A) mn(D) m + n - 1(C) m + n**SOL 1.58** Option (D) is correct. In a transportation problem with m origins and n destinations, if a basic feasible solution has less than m + n - 1 allocations (occupied cells), the problem is said to

be a degenerate transportation problem.

So, the basic condition for the solution to be optimal without degeneracy is.

Number of allocations = m + n - 1

**MCQ 1.59** A moving average system is used for forecasting weekly demand  $F_1(t)$  and  $F_2(t)$ GATE ME 2008 TWO MARK A moving average system is used for forecasting weekly demand  $F_1(t)$  and  $F_2(t)$ are sequences of forecasts with parameters  $m_1$  and  $m_2$ , respectively, where  $m_1$  and  $m_2(m_1 > m_2)$  denote the numbers of weeks over which the moving averages are taken. The actual demand shows a step increase from  $d_1$  to  $d_2$  at a certain time. Subsequently,

- (A) neither  $F_1(t)$  nor  $F_2(t)$  will catch up with the value  $d_2$
- (B) both sequences  $F_1(t)$  and  $F_2(t)$  will reach  $d_2$  in the same period

Page 40	ME GATE-08	www.gatehelp.com
	(C) $F_1(t)$ will attain the value $d_2$ before $F_2(t)$ (D) $F_2(t)$ will attain the value $d_2$ before $F_1(t)$	
SOL 1.59	Option (D) is correct. Here $F_1(t) \& F_2(t) =$ Forecastings $m_1 \& m_2 =$ Number of weeks A higher value of $m$ results in better smoothing. Since here $m_1$ of the latest demand would be more in $F_2(t)$ . Hence, $F_2(t)$ will attain the value of $d_2$ before $F_1(t)$ .	$> m_2$ the weightage
MCQ 1.60 GATE ME 2008 TWO MARK	For the network below, the objective is to find the length of the node $P$ to node $G$ . Let $d_{ij}$ be the length of directed arc from node $i$ to node $j$ . Let $S_j$ be the length of the shortest path from $P$ to node $j$ . We equations can be used to find $S_G$ ?	e shortest path from nich of the following
SOL 1.60	(A) $S_G = Min \{S_Q, S_R\}$ (C) $S_G = Min \{S_Q + d_{QG}, S_R + d_{RG}\}$ (D) $S_G = Min \{S_Q - d_{QG}, G_R + d_{RG}\}$ (D) $S_G = Min \{d_{QG}, d_{RG}\}$ (D) $S_G = Min \{d_{QG$	$\{Q_G,S_R-d_{RG}\}$
	For path $P$ - $R$ - $G$ , Length of the path $S_G = S_R + d_{RG}$	
	So, shortest path $S_G = \operatorname{Min}\{S_Q + d_{QG}, S_R + d_{RG}\}$	
GATE ME 2008 TWO MARK	\$R\$ The product structure of an assembly $$P$$ is shown in the figure	



Estimated demand for end product P is as follows

Week	1	2	3	4	5	6
Demand	1000	1000	1000	1000	1200	1200

ignore lead times for assembly and sub-assembly. Production capacity (per week) for component R is the bottleneck operation. Starting with zero inventory, the smallest capacity that will ensure a feasible production plan up to week 6 is

### **SOL 1.61** Option (C) is correct.

From the product structure we see that 2 piece of R is required in production of 1 piece P.

So,	demand	of	R	is	double of	of .	P	h	
-----	--------	----	---	----	-----------	------	---	---	--

Week	Demand (P)	$\begin{array}{c} \textbf{Demand} \\ (R) \end{array}$	Inventory level I = Production - Demand
1	1000	2000	R - 2000
2	1000	2000	2R - 4000
3	1000	2000	3R - 6000
4	1000	2000	4R - 8000
5	1200	2400	5R - 10400
6	1200	2400	6R - 12800

We know that for a production system with bottleneck the inventory level should be more than zero.

So,

 $6R - 12800 \ge 0$ 

For minimum inventory

$$6R - 12800 = 0$$
  
 $6R = 12800$   
 $R = 2133$   
 $\simeq 2200$ 

**ME GATE-08** 

Page 42

Hence, the smallest capacity that will ensure a feasible production plan up to week 6 is 2200.

MCQ 1.62 GATE ME 2008 TWO MARK One tooth of a gear having 4 module and 32 teeth is shown in the figure. Assume that the gear tooth and the corresponding tooth space make equal intercepts on the pitch circumference. The dimensions 'a' and 'b', respectively, are closest to



- (A) 6.08 mm, 4 mm
- (C) 6.28 mm, 4.3 mm

(B) 6.48 mm, 4.2 mm(D) 6.28 mm, 4.1 mm

**SOL 1.62** Option (D) is correct.



Given : m = 4, Z = 32, Tooth space = Tooth thickness = aWe know that,  $m = \frac{D}{Z}$ 

Pitch circle diameter,  $D = mZ = 4 \times 32 = 128 \text{ mm}$ And for circular pitch,  $P_c = \pi m = 3.14 \times 4 = 12.56 \text{ mm}$ We also know that circular pitch,

 $P_c$  = Tooth space + Tooth thickness  $P_c = a + a = 2a$  $a = \frac{P_c}{2} = \frac{12.56}{2} = 6.28 \text{ mm}$ 

From the figure, b = addendum + PRor  $\sin \phi = \frac{PQ}{OQ} = \frac{a/2}{64} = \frac{3.14}{64}$ 

$$\phi = \sin^{-1}(0.049) = 2.81^{\circ}$$
  

$$OP = 64 \cos 2.81^{\circ} = 63.9 \text{ mm}$$
  

$$PR = OR - OP = 64 - 63.9 = 0.1 \text{ mm} \quad OR = \text{Pitch circle radius}$$
  

$$b = m + PR = 4 + 0.1 = 4.1 \text{ mm}$$

And

Page 43		ME GATE-08	www.gatehelp.com
	Therefore, $a = 6.28 \text{ mm}$ and	d $b = 4.1  \text{mm}$	
MCQ 1.63 GATE ME 2008 TWO MARK	While cooling, a cubical ca shrinkage during the liquid volume of metal compensat (A) 2% (C) 8%	sting of side 40 mm un state, phase transition ted from the riser is (B) 7% (D) 9%	dergoes 3%, 4% and 5% volume and solid state, respectively. The
SOL 1.63	Option (B) is correct. Since metal shrinks on so temperature, linear dimensifinished casting to be obtain The riser can compensate for and not in the solid state. So, Volume of metal that c	lidification and contra ions of patterns are included. This is called the or volume shrinkage only ompensated from the r	cts further on cooling to room creased in respect of those of the "Shrinkage allowance". y in the liquid or transition stage iser $= 3\% + 4\% = 7\%$
MCQ 1.64 GATE ME 2008 ONE MARK	In a single point turning the equal. $\varphi$ is the principal characteristic chip flows in the orthogonal (A) $0^{\circ}$ (C) $60^{\circ}$	ool, the side rake angle utting edge angle and l plane. The value of $\varphi$ (B) 45° (D) 90°	e and orthogonal rake angle are its range is $0^{\circ} \leq \varphi \leq 90^{\circ}$ . The p is closest to
SOL 1.64	Option (D) is correct. Interconversion between AS (Orthogonal Rake System) $\tan \alpha_s = \sin \alpha_s$ where $\alpha_s = \operatorname{Sid} \alpha = \operatorname{ort} \alpha_s = \operatorname{ort} \alpha_s = \operatorname{ort} \alpha_s = \operatorname{ort} \alpha_s = \alpha$ ( $\tan \alpha_s = \sin \alpha_s$	SA (American Standard $\phi \tan \alpha - \cos \phi \tan i$ the rake angle hogonal rake angle nciple cutting edge ang lination angle ( $i = 0$ for Given) $\phi \tan \alpha - \cos \phi \tan (0^{\circ})$ $\phi \tan \alpha$ $\phi$ $\phi$	ds Association) system and ORS le = $0 \le \phi \le 90^{\circ}$ r ORS)
MCQ 1.65 GATE ME 2008 TWO MARK	A researcher conducts elect $6000 \text{ kg/m}^3$ ) of iron (ator 24, valency 4). Faraday's	rochemical machining ( nic weight 56, valency constant $= 96500$ coul	ECM) on a binary alloy (density 2) and metal (atomic weight omb/mole. Volumetric material

removal rate of the alloy is  $50 \text{ mm}^3/\text{s}$  at a current of 2000 A. The percentage of the

Brought to you by: <u>Nodia and Company</u> PUBLISHING FOR GATE

metal P in the alloy is closest to

(A) 40	(B) 25
(C) 15	(D) 79

**SOL 1.65** Option (B) is correct.

Given : 
$$\rho = 6000 \text{ kg/m}^3 = 6 \text{ gm/cm}^3, F = 96500 \text{ coulomb/mole}$$
  
 $MRR = 50 \text{ mm}^3/\text{s} = 50 \times 10^{-3} \text{ cm}^3/\text{s}, I = 2000 \text{ A}$   
For Iron : Atomic weight = 56

Valency = 2

For Metal P:Atomic weight = 24 Valency = 4

The metal Removal rate

$$MRR = \frac{eI}{F\rho}$$
  
50 × 10<sup>-3</sup> =  $\frac{e \times 2000}{96500 \times 6}$   
 $e = \frac{50 \times 10^{-3} \times 96500 \times 6}{2000} = 14.475$ 

Let the percentage of the metal P in the alloy is x.

So,

$$\frac{1}{e} = \frac{100 - x}{100} \times \frac{V_{Fe}}{A_{t_{Fe}}} + \frac{x}{100} \times \frac{V_{P}}{A_{tH}}$$

$$\frac{1}{14.475} = \frac{100 - x}{100} \times \frac{2}{56} + \frac{x}{100} \times \frac{4}{24}$$

$$\frac{1}{14.475} = \left(1 - \frac{x}{100}\right)\frac{1}{28} + \frac{x}{100} \times \frac{1}{6}$$

$$\frac{1}{14.475} = x\left[\frac{1}{600} - \frac{1}{2800}\right] + \frac{1}{28}$$

$$\frac{1}{14.475} - \frac{1}{28} = x \times \frac{11}{8400}$$

$$\frac{541}{16212} = \frac{11x}{8400}$$

$$x = \frac{541 \times 8400}{16212 \times 11} \simeq 25$$

MCQ 1.66 In a single pass rolling operation, a 20 mm thick plate with plate width of 100 mm GATE ME 2008 TWO MARK , is reduced to 18 mm. The roller radius is 250 mm and rotational speed is 10 rpm. The average flow stress for the plate material is 300 MPa. The power required for the rolling operation in kW is closest to (A) 15.2 (B) 18.2

(A)	15.2	(B)	18.2
(C)	30.4	(D)	45.6

**SOL 1.66** Option None of these.

Given :  $t_i = 20 \text{ mm}$ ,  $t_f = 18 \text{ mm}$ , b = 100 mm, R = 250 mm, N = 10 rpm,  $\sigma_0 = 300 \text{ MPa}$ We know, Roll strip contact length is given by,  $L = heta imes R = \sqrt{rac{t_i - t_f}{R}} imes R$ 

	$=\sqrt{R(t_i-t_f)}$
So,	$L = \sqrt{250 \times 10^{-3} (20 - 18) 10^{-3}}$
	$=22.36 imes 10^{-3}$
Rolling load,	$F = Lb\sigma_0 = 22.36  imes 10^{-3}  imes 100  imes 10^{-3}  imes 300  imes 10^6$
	$= 670.8 \mathrm{kN}$
Power	$P = F \times v = 670.8 \times \left(\frac{\pi DN}{60}\right)$
	$= 670.8 \times \left(\frac{3.14 \times 0.5 \times 10}{60}\right) = 175.5 \mathrm{kW}$

MCQ 1.67	In arc welding of a butt joint, the welding speed is to be selected such that highest
GATE ME 2008	cooling rate is achieved. Melting efficiency and heat transfer efficiency are 0.5 and
I WO MARK	0.7, respectively. The area of the weld cross section is $5 \text{ mm}^2$ and the unit energy
	required to melt the metal is $10 \text{ J/mm}^3$ . If the welding power is $2 \text{ kW}$ , the welding
	speed in mm/s is closest to
	(A) 4 (B) 14
	(C) 24 (D) 34
SOL 1.67	Option (B) is correct. Given : $n_m = 0.5$ , $n_h = 0.7$ , $A = 5 \text{ mm}^2$
	$E_{\rm r} = 10  \text{J/mm}^3$ , $P = 2  \text{kW}$ , $V  (\text{mm/s}) = 3$
	Total energy required to melt.
	$E = E_u \times A \times V = 10 \times 5 \times V = 50 V \text{ J/sec}$
	Power supplied for welding,
	$P_s = P  imes \eta_h  imes \eta_m = 2  imes 10^3  imes 0.5  imes 0.7 = 700  { m W}$
	From energy balance,
	Energy required to $melt = Power$ supplied for welding
	$50 V = 700 \qquad \Rightarrow  V = 14 \text{ mm/sec}$
MCQ 1.68	In the deep drawing of cups, blanks show a tendency to wrinkle up around the
GATE ME 2008 TWO MARK	periphery (flange). The most likely cause and remedy of the phenomenon are, respectively,
	(A) Buckling due to circumferential compression; Increase blank holder pressure
	(B) High blank holder pressure and high friction; Reduce blank holder pressure and apply lubricant
	(C) High temperature causing increase in circumferential length; Apply coolant to blank
	(D) Buckling due to circumferential compression; decrease blank holder pressure
SOL 1.68	Option (A) is correct.
	Seamless cylinders and tubes can be made by hot drawing or cupping.

Visit us at: www.nodia.co.in

The thickness of the cup is reduced and its length increased by drawing it through a series of dies having reduced clearance between the die and the punch. Due to reduction in its thickness, blanks shows a tendency to wrinkle up around the periphery because of buckling due to circumferential compression an due to this compression blank holder pressure increases.

MCQ 1.69

GATE ME 2008 TWO MARK The figure shows an incomplete schematic of a conventional lather to be used for cutting threads with different pitches. The speed gear box  $U_v$  is shown and the feed gear box  $U_s$  is to be placed. P, Q, R and S denote locations and have no other significance. Changes in  $U_v$  should NOT affect the pitch of the thread being cut and changes in  $U_s$  should NOT affect the cutting speed.



The correct connections and the correct placement of  $U_s$  are given by

- (A) Q and E are connected.  $U_s$  is placed between P and Q.
- (B) S and E are connected.  $U_s$  is placed between R and S
- (C) Q and E are connected.  $U_s$  is placed between Q and E
- (D) S and E are connected.  $U_s$  is placed between S and E
- **SOL 1.69** Option (C) is correct.

The feed drive serves to transmit power from the spindle to the second operative unit of the lathe, that is, the carriage. It, thereby converts the rotary motion of the spindle into linear motion of the carriage.

So, Q and E are connected &  $U_s$  is placed between Q and E.

**MCQ 1.70** A displacement sensor (a dial indicator) measure the lateral displacement of a mandrel mounted on the taper hole inside a drill spindle. The mandrel axis is an extension of the drill spindle taper hole axis and the protruding portion of the mandrel surface is perfectly cylindrical measurements are taken with the sensor placed at two positions P and Q as shown in the figure. The reading are recorded as  $R_x =$  maximum deflection minus minimum deflection, corresponding to sensor position at X, over one rotation.



- If  $R_P = R_Q > 0$ , which one of the following would be consistent with the observation ?
- (A) The drill spindle rotational axis is coincident with the drill spindle taper hole axis
- (B) The drill spindle rotational axis intersects the drill spindle taper hole axis at point P
- (C) The drill spindle rotational axis is parallel to the drill spindle taper hole axis
- (D) The drill spindle rotational axis intersects the drill spindle taper hole axis at point Q
- **SOL 1.70** Option (C) is correct.

A dial indicator (gauge) or clock indicator is a very versatile and sensitive instrument. It is used for :

- (i) determining errors in geometrical form, for example, ovality, out-of roundness, taper etc.
- (ii) determining positional errors of surface

(iii) taking accurate measurements of deformation.

Here equal deflections are shown in both the sensor P and sensor Q. So drill spindle rotational axis is parallel to the drill spindle taper hole axis.

### Common Data for Questions 71, 72 & 73:

In the figure shown, the system is a pure substance kept in a piston-cylinder arrangement. The system is initially a two-phase mixture containing 1 kg of liquid and 0.03 kg of vapour at a pressure of 100 kPa. Initially, the piston rests on a set of stops, as shown in the figure. A pressure of 200 kPa is required to exactly balance the weight of the piston and the outside atmospheric pressure. Heat transfer takes place into the system until its volume increases by 50%. Heat transfer to the system occurs in such a manner that the piston, when allowed to move, does so in a very slow (quasi-static/quasi-equilibrium) process. The thermal reservoir from which heat is transferred to the system has a temperature of  $400^{\circ}$  C. Average temperature

#### ME GATE-08

of the system boundary can be taken as  $175^{\circ}$  C. The heat transfer to the system is 1 kJ, during which its entropy increases by 10 J/K.



Specific volume of liquid  $(\nu_f)$  and vapour  $(\nu_g)$  phases, as well as values of saturation temperatures, are given in the table below.

Pressure (kPa)	Saturation temperature, $T_{\rm sat}(^{\circ}{ m C})$	$ u_f({ m m}^3/{ m kg})$	$ u_g({ m m}^3/{ m kg})$
100	100	0.001	0.1
200	200	0.0015	0.002

MCQ 1.71At the end of the process, which one of the following situations will be true ?GATE ME 2008<br/>TWO MARK(A) superheated vapour will be left in the system

- (B) no vapour will be left in the system
- (C) a liquid + vapour mixture will be left in the system
- (D) the mixture will exist at a dry saturated vapour state
- **SOL 1.71** Option (A) is correct.

When the vapour is at a temperature greater than the saturation temperature, it is said to exist as super heated vapour. The pressure & Temperature of superheated vapour are independent properties, since the temperature may increase while the pressure remains constant. Here vapour is at  $400^{\circ}$ C & saturation temperature is  $200^{\circ}$ C.

So, at 200 kPa pressure superheated vapour will be left in the system.

MCQ 1.72	The work done by the system	during the process is
GATE ME 2008	(A) 0.1 kJ	(B) 0.2 kJ
I WO MARK	(C) 0.3 kJ	(D) $0.4 \text{ kJ}$

**SOL 1.72** Option (D) is correct. Given :  $p_1 = 100 \text{ kPa}, p_2 = 200 \text{ kPa}$ 

TWO MARK

**SOL 1.73** 

Let,  $\nu_1 = \nu$ Now, given that Heat transfer takes place into the system until its volume increases by 50% So,  $\nu_2 = \nu + 50\% \text{ of } \nu$ Now, for work done by the system, we must take pressure is  $p_2 = 200 \text{ kPa}$ , because work done by the system is against the pressure  $p_2$  and it is a positive work done. From first law of thermodynamics, dQ = dU + dW...(i) But for a quasi-static process, T = ConstantTherefore, change in internal energy is dU = 0From equation (i)  $dQ = dW = pd\nu$  $dW = pd\nu$  $= p[\nu_2 - \nu_1]$ For initial condition at 100 kPa, volume  $u_1 = m_{liquid} imes rac{1}{
ho_f} + m_{vapour} imes rac{1}{
ho_a}$  $egin{aligned} rac{1}{
ho_f} &= 
u_f = 0.001, \ rac{1}{
ho_g} = 
u_g = 0.1 \ m_{liquid} &= 1 \ \mathrm{kg}, \ m_{vapour} = 0.03 \ \mathrm{kg} \end{aligned}$ Here  $u_1 = 1 \times 0.001 + 0.03 \times 0.1$ So  $\nu_2 = \frac{3}{2}\nu_1 = \frac{3}{2} \times 4 \times 10^{-3} = 6 \times 10^{-3} \,\mathrm{m}^3$  $=200 \times 10^{3} \left[ \frac{3\nu}{2} - \nu \right]$  $=200 \times [6 \times 10^{-3} - 4 \times 10^{-3}]$  $= 200 \times 2 \times 10^{-3} = 0.4 \text{ kJ}$ **MCQ 1.73** The net entropy generation (considering the system and the thermal reservoir GATE ME 2008 together) during the process is closest to (A) 7.5 J/K (B) 7.7 J/K (C) 8.5 J/K(D) 10 J/K Option (C) is correct.  $\Delta s_{net} = (\Delta s)_{system} + (\Delta s)_{surrounding}$ ...(i) And it is given that,  $(\Delta s)_{system} = 10 \text{ kJ}$  $(\Delta s)_{surrounding} = \left(\frac{Q}{T}\right)_{surrounding}$ Also, Heat transferred to the system by thermal reservoir,

$$T = 400 \,^{\circ} \,\mathrm{C} = (400 + 273) \,\mathrm{K} = 673 \,\mathrm{K}$$
$$Q = 1 \,\mathrm{kJ}$$
$$(\Delta s)_{surrounding} = \frac{1000}{673} = 1.485 \,\mathrm{J/K}$$

From equation (i)

 $(\Delta s)_{net} = 10 - 1.485 = 8.515 \,\mathrm{J/K}$ 

(Take Negative sign, because the entropy of surrounding decrease due to heat transfer to the system.)

### Common Data for Questions 74 and 75 :

Consider the Linear Programme (LP) Max 4x + 6ySubject to

$$3x + 2y \le 6$$
  
$$2x + 3y \le 6$$
  
$$x, y \ge 0$$

**MCQ 1.74** GATE ME 2008 TWO MARK

After introducing slack variables s and t, the initial basic feasible solution is represented by the table below (basic variables are s = 6 and t = 6, and the objective function value is 0)

	-4	-6	<b>n</b> 0	0	0
s	3	2	1	0	6
t	2	3	0	1	6
	x	y	S	t	RHS

After some simplex iterations, the following table is obtained

	0	0	0	2	12
8	5/3	0	1	-1/3	2
y	2/3	1	0	1/3	2
	x	y	8	t	RHS

From this, one can conclude that

- (A) the LP has a unique optimal solution
- (B) the LP has an optimal solution that is not unique
- (C) the LP is infeasible
- (D) the LP is unbounded

**SOL 1.74** Option (B) is correct.

The LP has an optimal solution that is not unique, because zero has appeared in

Broug	ht to yo	ou by: <u>No</u>	dia and	Company	r
		PU	BLISHI	NG FOR	GATE

0							
	the non-basic variable $(x \text{ and } x)$	y) column, in optimal solution.					
MCQ 1.75	The dual for the LP in $Q$ . 29 is						
GATE ME 2008 TWO MARK	(A) $\operatorname{Min} 6u + 6v$	(B) Max $6u + 6v$					
	subject to	subject to					
	$3u + 2v \ge 4$	$3u + 2v \le 4$					
	$2u + 3v \ge 6$	$2u + 3v \le 6$					
	$u, v \ge 0$	$u, v \ge 0$					
	(C) Max $4u + 6v$	(D) Min $4u + 6v$					
	subject to	subject to					
	$3u + 2v \ge 6$	$3u + 2v \le 6$					
	$2u + 3v \ge 6$	$2u + 3v \le 6$					
	$y, v \ge 0$	$y, y \ge 0$					
SOL 1.75	Uption (A) is correct.						
	The general form of LP is						
	Subject to $AY \leq B$						
	And dual of above ID is numerated by						
	$\operatorname{Min} Z = B^T Y$						
	Subject to $A^T Y \ge$						
	So, the dual is $Min 6u + 6v$						
	Subject to $3u + 2v \ge$	4					
	$2u + 3v \ge$	6					

**ME GATE-08** 

Page 51

### Statement for Linked Answer Questions 76 and 77 :

 $u, v \ge 0$ 

A cylindrical container of radius R = 1 m, wall thickness 1 mm is filled with water up to a depth of 2 m and suspended along its upper rim. The density of water is 1000 kg/m<sup>3</sup> and acceleration due to gravity is  $10 \text{ m/s}^2$ . The self-weight of the cylinder is negligible. The formula for hoop stress in a thin-walled cylinder can be used at all points along the height of the cylindrical container.

www.gatehelp.com





$$\sigma_x = \sigma_a = \frac{p \times D}{4t} = \frac{p \times 2R}{4t} \qquad \dots (i)$$

$$p = \text{Pressure of the fluid inside the shell}$$

$$t \ 1 \ \text{m depth is,}$$

Here,

So, pressure at 1 m depth is,

$$p = \rho g h = 1000 \times 10 \times 1 = 10^4 \,\mathrm{N/m^2}$$

From equation (i),

$$\sigma_a = \frac{10^4 \times 2 \times 1}{4 \times 10^{-3}} = 5 \times 10^6 \,\mathrm{N/m^2} = 5 \,\mathrm{MPa}$$

And hoop or circumferential stress,

$$\sigma_y = \sigma_c = \frac{p \times D}{2t}$$
  
 $\sigma_c = \frac{10^4 \times 2}{2 \times 10^{-3}} = 10 \times 10^6 \,\mathrm{N/m^2} = 10 \,\mathrm{MPa}$ 

MCQ 1.77If the Young's modulus and Poisson's ratio of the container material are 100 GPaGATE ME 2008<br/>TWO MARKand 0.3, respectively, the axial strain in the cylinder wall at mid-depth is<br/>(A)  $2 \times 10^{-5}$ <br/>(C)  $7 \times 10^{-5}$ (B)  $6 \times 10^{-5}$ <br/>(D)  $1.2 \times 10^{-4}$ 

**SOL 1.77** Option (A) is correct.

Given : v or  $\frac{1}{m} = 0.3$ ,  $E = 100 \text{ GPa} = 100 \times 10^9 \text{ Pa}$ Axial strain or longitudinal strain at mid – depth is,

$$\sigma_a = \sigma_x = rac{pD}{2tE} \Big( rac{1}{2} - rac{1}{m} \Big)$$

Substitute the values, we get

Brought to you by: Nodia and Company PUBLISHING FOR GATE

Visit us at: www.nodia.co.in

$$\sigma_{a} = \frac{10^{4} \times 2 \times 1}{2 \times 10^{-3} \times 100 \times 10^{9}} \left(\frac{1}{2} - 0.3\right)$$
  
$$\sigma_{a} = \frac{10^{4}}{10^{8}} \left(\frac{1}{2} - 0.3\right) = 10^{-4} \times 0.2 = 2 \times 10^{-5}$$

### Statement for Linked Answer Questions 78 and 79:

A steel bar of  $10 \times 50$  mm is cantilevered with two M 12 bolts (P and Q) to support a static load of 4 kN as shown in the figure.



In this figure  $W_S$  represent the primary shear load whereas  $W_{S1}$  and  $W_{S2}$  represent the secondary shear loads.

Given :  $A = 10 \times 50 \text{ mm}^2$ , n = 2,  $W = 4 \text{ kN} = 4 \times 10^3 \text{ N}$ 

We know that primary shear load on each bolt acting vertically downwards,

$$W_s = \frac{W}{n} = \frac{4 \text{ kN}}{2} = 2 \text{ kN}$$

Since both the bolts are at equal distances from the centre of gravity G of the two bolts, therefore the secondary shear load on each bolt is same. For secondary shear load, taking the moment about point G,

Brought to you by: Nodia and Company PUBLISHING FOR GATE ME GATE-08

 $W_{s1} \times r_1 + W_{s2} \times r_2 = W \times e$  $r_1 = r_2$  and  $W_{s1} = W_{s2}$  $2r_1 W_{s1} = 4 \times 10^3 \times (1.7 + 0.2 + 0.1)$ So,  $2 \times 0.2 \times W_{s1} = 4 \times 10^3 \times 2$  $W_{\rm s1} = \frac{8 \times 10^3}{2 \times 0.2} = 20 \times 10^3 = 20 \, \rm kN$ **MCQ 1.79** The resultant shear stress on bolt P is closest to (A) 132 MPa GATE ME 2008 (B) 159 MPa TWO MARK (C) 178 MPa (D) 195 MPa **SOL 1.79** Option (B) is correct. From the figure, resultant Force on bolt P is  $F = W_{s2} - W_s = 20 - 2 = 18 \text{ kN}$ Shear stress on bolt P is,  $\tau = \frac{F}{\text{Area}}$  $M\!12$  Means bolts have 12 mm diameter  $=\frac{18 \times 10^{3}}{\frac{\pi}{4} \times (12 \times 10^{-3})^{2}} = 159.23 \,\mathrm{MPa} \simeq 159 \,\mathrm{MPa}$ Statement for linked Answer questions 80 & 81: The gap between a moving circular plate and a stationary surface is being continuously reduced, as the circular plate comes down at a uniform speed V

towards the stationary bottom surface, as shown in the figure. In the process, the fluid contained between the two plates flows out radially. The fluid is assumed to be incompressible and inviscid.



**MCQ 1.80** The radial velocity  $V_r$  at any radius r, when the gap width is h, is GATE ME 2008 TWO MARK
(A)  $V_r = \frac{Vr}{2h}$ (B)  $V_r = \frac{Vr}{h}$ (C)  $V_r = \frac{2Vh}{r}$ (D)  $V_r = \frac{Vh}{r}$ 

Brought to you by: Nodia and Company PUBLISHING FOR GATE Visit us at: www.nodia.co.in

### **SOL 1.80** Option (A) is correct.



Here Gap between moving & stationary plates are continuously reduced, so we can say that

Volume of fluid moving out radially

= Volume of fluid displaced by moving plate within radius r Volume displaced by the moving plate

= Velocity of moving plate × Area=  $V \times \pi r^2$  ...(i) Volume of fluid which flows out at radius r

$$= V_r \times 2\pi r \times h \mathbf{Q} \qquad \dots (ii)$$
  
Equating equation (i) & (ii),  
$$V \times \pi r^2 = V_r \times 2\pi r h$$
$$Vr = 2V_r h \Rightarrow V_r = \frac{\mathbf{Q}r}{2h}$$

### **Alternate Method :**

Apply continuity equation at point (i) & (ii),

$$egin{aligned} A_1 \, V_1 &= A_2 \, V_2 \ V imes \, \pi r^2 &= V_r imes 2 \pi r h \ V_r &= rac{Vr}{2h} \end{aligned}$$

MCQ 1.81The radial component of the fluid acceleration at r = R isGATE ME 2008<br/>TWO MARK(A)  $\frac{3 V^2 R}{4h^2}$ (B)  $\frac{V^2 R}{4h^2}$ (C)  $\frac{V^2 R}{2h^2}$ (D)  $\frac{V^2 h}{2R^2}$ 

### SOL 1.81

From previous part of question,

Option (B) is correct.

$$V_r = \frac{Vr}{2h}$$

Acceleration at radius r is given by

$$a_r = V_r \times \frac{dV_r}{dr} = V_r \times \frac{d}{dr} \left[ \frac{Vr}{2h} \right] = V_r \times \frac{V}{2h}$$
 ...(i)

At r = R

Brought to you by: Nodia and Company PUBLISHING FOR GATE

$$a_r = \frac{VR}{2h} \times \frac{V}{2h} = \frac{V^2R}{4h^2}$$

### Statement for Linked Answer Questions 82 and 83:

Orthogonal turning is performed on a cylindrical workpiece with the shear strength of 250 MPa. The following conditions are used: cutting velocity is 180 m/min, feed is 0.20 mm/rev, depth of cut is 3 mm, chip thickness ratio = 0.5. The orthogonal rake angle is 7°. Apply Merchant's theory for analysis.

<b>MCQ 1.82</b> GATE ME 2008 TWO MARK	The shear plane angle (in degree (A) 52, 320 N	e) and the shear force respectively are (B) 52, 400 N					
	(C) 28, 400 N	(D) 28, 320 N					
SOL 1.82	Option (D) is correct. Given : $\tau_s = 250$ MPa, $V = 180$ m $d = 3$ mm, $r = 0.5$ , $\alpha = 7^{\circ}$ We know from merchant's theor Shear plane angle tar	$n/\min, f = 0.20 \text{ mm/rev.}$					
	Average stress on the shear plan	$\phi = \frac{0.5 \cos 7^{\circ}}{1 - 0.7 \sin 7^{\circ}} = \frac{0.496}{0.915} = 0.54$ $\phi = \tan^{-1}(0.54) = 28.36 \approx 28^{\circ}$ he area are $\tau_s = \frac{F_s}{A_s} \qquad \Rightarrow F_s = \tau_s \times A_s$					
	where, $A_s$ is the shear plane are	$a = \frac{bt}{\sin\phi}$					
	for orthogonal operation $b \cdot t = d \cdot f$						
	So,	$F_s = \frac{\tau_s \times d \times f}{\sin \phi}$					
		$F_s = \frac{250 \times 3 \times 0.20}{\sin 28^\circ} = 319.50 \simeq 320 \mathrm{N}$					
MCQ 1.83	The cutting and frictional forces, respectively, are						
GATE ME 2008 TWO MARK	(A) 568 N, 387 N	(B) 565 N, 381 N					
1 000 000000	(C) 440 N, 342 N	(D) 480 N, 356 N					
SOL 1.83	Option (B) is correct. Now we have to find cutting for From merchant's theory, $2\phi + \beta -$	ce $(F_c)$ and frictional force $(F_t)$ . $\alpha = 90^{\circ}$					
	$eta=90^\circ+lpha-2\phi$						

 $=90^{\circ} + 7 - 2 \times 28 = 41^{\circ}$ 

We know that

$$\frac{F_c}{F_s} = \frac{\cos(\beta - \alpha)}{\cos(\phi + \beta - \alpha)} \qquad F_s = \text{Share force}$$

$$F_c = 320 \times \frac{\cos(41^\circ - 7^\circ)}{\cos(28^\circ + 41^\circ - 7^\circ)}$$

$$= 320 \times 1.766 \simeq 565 \text{ N}$$
And
$$F_s = F_c \cos \phi - F_t \sin \phi$$
So,
$$F_t = \frac{F_c \cos \phi - F_s}{\sin \phi}$$

$$F_t = \frac{565 \times \cos 28^\circ - 320}{\sin 28^\circ} = \frac{178.865}{0.47}$$

$$= 381.56 \text{ N} \simeq 381 \text{ N}$$

- )

### Statement for linked Answer Questions 84 and 85 :

In the feed drive of a Point-to-Point open loop CNC drive, a stepper motor rotating at 200 steps/rev drives a table through a gear box and lead screw-nut mechanism (pitch=4 mm, number of starts=1). The gear ratio =  $\left(\frac{\text{Output rotational speed}}{\text{Input rotational speed}}\right)$  is given by  $U = \frac{1}{4}$ . The stepper motor (driven by voltage pulses from a pulse generator) executes 1 start in the failer of the failer generator) executes 1 step/pulse of the pulse generator. The frequency of the pulse train from the pulse generator is f = 10,000 pulses per minute.



#### The basic Length Unit (BLU), i.e., the table movement corresponding to 1 pulse of **MCQ 1.84** GATE ME 2008 the pulse generator, is TWO MARK (A) 0.5 microns(B) 5 microns

(C) 50 microns (D) 500 microns

Option (B) is correct. **SOL 1.84** 

Given : N = 200 step/rev., p = 4 mm,  $U = \frac{1}{4}$ , f = 10000 Pulse/min.

In a CNC machine basic length unit (BLU) represents the smallest distance.

Revolution of motor in one step  $=\frac{1}{200}$  rev./step

Movement of lead screw  $=\frac{1}{200} \times \frac{1}{4} = \frac{1}{800}$  rev. of load screw

Movement from lead screw is transferred to table.

i.e. Movement of table  $=\frac{1}{800} \times \text{Pitch} = \frac{1}{800} \times 4 = \frac{1}{200}$ 

Brought to you by: Nodia and Company PUBLISHING FOR GATE

Visit us at: www.nodia.co.in

S

$$= 0.005 = 5$$
 microns.

A customer insists on a modification to change the BLU of the CNC drive to 10 **MCQ 1.85** microns without changing the table speed. The modification can be accomplished GATE ME 2008 TWO MARK by (A) changing U to  $\frac{1}{2}$  and reducing f to  $\frac{f}{2}$ (B) changing U to  $\frac{1}{8}$  and increasing f to 2f(C) changing U to  $\frac{1}{2}$  and keeping f unchanged (D) keeping U unchanged and increasing f to 2fOption (C) is correct. **SOL 1.85** If we change the gear ratio by a factor  $\frac{1}{2}$  and f remains unchanged, then  $BLU = Revolution of motor \times Gear ratio \times pitch$  $=\frac{1}{200} \times \frac{1}{2} \times 4 = \frac{1}{100} = 10$  micros We see that f is unchanged and value of Gear ratio is changed by  $\frac{1}{2}$ . <u>g a t e</u> help

Answer Sheet									
1.	(C)	18.	(A)	35.	(B)	52.	(A)	69.	(C)
2.	(D)	19.	(C)	36.	(B)	53.	(B)	70.	(C)
3.	(B)	20.	(C)	37.	(D)	54.	(B)	71.	(A)
4.	(A)	21.	(A)	38.	(C)	55.	(C)	72.	(D)
5.	(C)	22.	(B)	39.	(D)	56.	(D)	73.	(C)
6.	(D)	23.	(B)	40.	(A)	57.	(C)	74.	(B)
7.	(D)	24.	(D)	41.	(B)	58.	(D)	75.	(A)
8.	(D)	25.	(A)	42.	(B)	59.	(D)	76.	(B)
9.	(D)	26.	(D)	43.	(A)	60.	(C)	77.	(A)
10.	(D)	27.	(B)	44.	(C)	61.	(C)	78.	(A)
11.	(B)	28.	(C)	45.	(C)	62.	(D)	79.	(B)
12.	(D)	29.	(A)	46.	(B)	63.	(B)	80.	(A)
13.	(B)	30.	(C)	47.	(A)	64.	(D)	81.	(B)
14.	(C)	31.	(D)	48.	(C)	65.	(B)	82.	(D)
15.	(D)	32.	(B)	49.	(A)	66.	(*)	83.	(B)
16.	(B)	33.	(A)	50.	(D)	67.	(B)	84.	(B)
17.	(C)	34.	(B)	51.	(*)	68.	(A)	85.	(C)
					IIUT	۲ T			

## GATE Multiple Choice Questions For Mechanical Engineering

### By NODIA and Company

Available in Three Volumes

# Features:

- The book is categorized into chapter and the chapter are sub-divided into units
- Unit organization for each chapter is very constructive and covers the complete syllabus
- Each unit contains an average of 40 questions
- The questions match to the level of GATE examination
- Solutions are well-explained, tricky and consume less time. Solutions are presented in such a way that it enhances you fundamentals and problem solving skills
- There are a variety of problems on each topic
- Engineering Mathematics is also included in the book

## Contents

## VOLUME-1 Applied Mechanics and Design

### UNIT 1. Engineering Mechanics

- 1.1 Equilibrium of forces
- 1.2 Structure
- 1.3 Friction
- 1.4 Virtual work
- 1.5 Kinematics of particle
- 1.6 Kinetics of particle
- 1.7 Plane kinematics of rigid bodies
- 1.8 Plane kinetics of rigid bodies

### UNIT 2. Strength of Material

- 2.1 Stress and strain
- 2.2 Axial loading
- 2.3 Torsion
- 2.4 Shear force and bending moment

- 2.5 Transformation of stress and strain
- 2.6 Design of beams and shafts
- 2.7 Deflection of beams and shafts
- 2.8 Column
- 2.9 Energy methods

### UNIT 3. Machine Design

- 3.1 Design for static and dynamic loading
- 3.2 Design of joints
- 3.3 Design of shaft and shaft components
- 3.4 Design of spur gears
- 3.5 Design of bearings
- 3.6 Design of clutch and brakes

### UNIT 4. Theory of Machine

- 4.1 Analysis of plane mechanism
- 4.2 Velocity and acceleration
- 4.3 Dynamic analysis of slider-crank and cams
- 4.4 Gear-trains
- 4.5 Flywheel
- 4.6 vibration

### VOLUME-2 Fluid Mechanics and Thermal Sciences

### UNIT 5. Fluid Mechanics

- 5.1 Basic concepts and properties of fluids
- 5.2 Pressure and fluid statics
- 5.3 Fluid kinematics and Bernoulli Equation
- 5.4 Flow analysis using control volume
- 5.5 Flow analysis using differential method
- 5.6 Internal flow
- 5.7 External flow
- 5.8 Open channel flow
- 5.9 Turbomachinary

### UNIT 6. Heat Transfer

- 6.1 Basic concepts and modes of Heat transfer
- 6.2 Fundamentals of conduction
- 6.3 Steady heat conduction
- 6.4 Transient heat conduction
- 6.5 Fundamentals of convection
- 6.6 Free convection
- 6.7 Forced convection
- 6.8 Fundamentals of thermal radiation
- 6.9 Radiation Heat transfer
- 6.10 Heat exchangers.

### UNIT 7. Thermodynamics

- 7.1 Basic concepts and Energy analysis
- 7.2 Properties of pure substances
- 7.3 Energy analysis of closed system
- 7.4 Mass and energy analysis of control volume
- 7.5 Second law of thermodynamics
- 7.6 Entropy
- 7.7 Gas power cycles
- 7.8 Vapour and combined power cycles
- 7.9 Refrigeration and air conditioning

### VOLUME-3 Manufacturing and Industrial Engineering

### **UNIT 8. Engineering Materials**

8.1 Structure and properties of engineering materials, heat treatment, stress-strain diagrams for engineering materials

### UNIT 9. Metal Casting:

Design of patterns, moulds and cores; solidification and cooling; riser and gating design, design considerations.

### UNIT 10. Forming:

Plastic deformation and yield criteria; fundamentals of hot and cold working processes; load estimation for bulk (forging, rolling, extrusion, drawing) and sheet (shearing, deep drawing, bending) metal forming processes; principles of powder metallurgy.

### UNIT 11. Joining:

Physics of welding, brazing and soldering; adhesive bonding; design considerations in welding.

### UNIT 12. Machining and Machine Tool Operations:

Mechanics of machining, single and multi-point cutting tools, tool geometry and materials, tool life and wear; economics of machining; principles of non-traditional machining processes; principles of work holding, principles of design of jigs and fixtures

### UNIT 13. Metrology and Inspection:

Limits, fits and tolerances; linear and angular measurements; comparators; gauge design; interferometry; form and finish measurement; alignment and testing methods; tolerance analysis in manufacturing and assembly.

### UNIT 14. Computer Integrated Manufacturing:

Basic concepts of CAD/CAM and their integration tools.

### UNIT 15. Production Planning and Control:

Forecasting models, aggregate production planning, scheduling, materials requirement planning

### **UNIT 16.** Inventory Control:

Deterministic and probabilistic models; safety stock inventory control systems.

### UNIT 17. Operations Research:

Linear programming, simplex and duplex method, transportation, assignment, network flow models, simple queuing models, PERT and CPM.

### UNIT 18. Engineering Mathematics:

- 18.1 Linear Algebra
- 18.2 Differential Calculus
- 18.3 Integral Calculus
- 18.4 Differential Equation
- 18.5 Complex Variable
- 18.6 Probability & Statistics
- 18.7 Numerical Methods